

Kitaev model

① Topo QC \Rightarrow 有一定纠错能力 \Rightarrow motivation 1995

② Kitaev

③ Kitaev model / hamiltonian

Kitaev - Heisenberg model

motivation: α -RauU₃ (?)

④ Entanglement Entropy \rightarrow Category theory

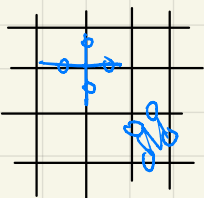
Levin - Wen model

Kitaev model (初步)

目的: 了解其基本特点

① Toric-code model

$$H = -\sum_s A_s - \sum_p B_p$$



s : star

p : plaquette

坐标在 Bond

$$A_s = \prod_{j \in s} \sigma_j^x$$

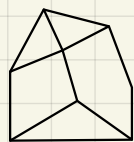
$$B_p = \prod_{i \in p} \sigma_i^z$$

$$\sigma_x \sigma_z = -\sigma_z \sigma_x$$

0/2个相同点(j)

基本性质, $[A_s, A_{s'}] = [B_p, B_{p'}] = [A_s, B_p] = 0$

推广到 ∇ 结构



所有算子对易 (仅限 2d)

$$A_s = A_s^\dagger, B_p = B_p^\dagger$$

$$A_s^2 = B_p^2 = 1$$

$$\prod_s A_s = \prod_p B_p = 1$$

(所有j计算2次)

求解 \Rightarrow 困难
 $\left\{ \begin{array}{l} \text{sym} \\ \text{一般少量, 如平移} \end{array} \right.$

\Rightarrow $\left\{ \begin{array}{l} \text{QWT} \quad (\text{严格可解}) \\ \text{② } \epsilon_0, \epsilon_{\text{emitted}} \dots \\ \text{③ } \text{GS Degeneracy} \Rightarrow \text{Topo 有关} \end{array} \right.$
 Toric $\textcircled{0}$
 eg. TR $\Leftrightarrow |\phi\rangle$ 和 $T|\phi\rangle$

$\Rightarrow [A_s, H] = [B_p, H] = 0$
 $\left\{ \begin{array}{l} A, B \text{ 对易} \end{array} \right.$

$|\text{GS}\rangle \Rightarrow A_s, B_p, H$ 共同本征态

① $N \times N \Rightarrow 4N^2/2 = 2N^2$ (虚/自由度) \Rightarrow Hilbert space 2^{2N}

周期性边界条件 $\text{real } 2N^2 - 2$
 2^{2N-2}
 \Downarrow
 4重简并

$E_g = -2N^2 \times 1 - 2N^2 \times 1$
 $= -4N^2 \quad \text{令 } A_s = B_p = 1$

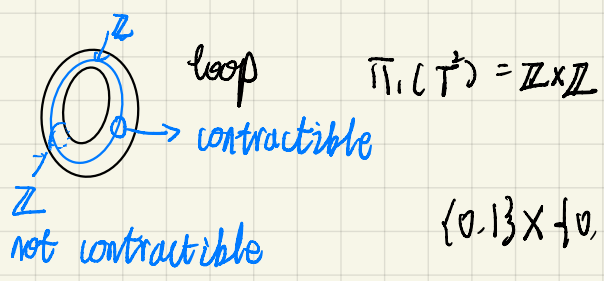
$A_s: 1 \rightarrow -1 \quad \epsilon_1, -\epsilon_0 \sim 2.$ gapped.

GS \Rightarrow projector 写不出来. 构造出来

$|\text{G}\rangle = \prod_p \left(\frac{1+B_p}{2} \right) \prod_s \left(\frac{1+A_s}{2} \right) |\phi\rangle$ (非0的基态)

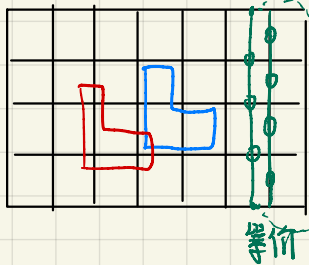
$B_p |\text{G}\rangle = |\text{G}\rangle$
 $B_p (1+B_p) = B_p + B_p^2 = 1+B_p$

体现其几何性质 / Topo 性质 Degeneracy



几何 loop $\begin{cases} \text{contractible} \\ \text{not} \dots \end{cases}$

周期性边界条件



$t_4 = \prod B_p$ loop contractible
 $t_4 |u\rangle = |u\rangle$
 $t_5 = \prod A_s$ Trivial
 $t_5 |u\rangle = |u\rangle$

① 物理上 loop

② 两种 loop 为何不同.

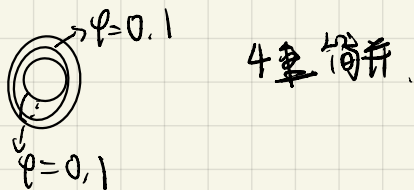
代数: $t_5 t_5$ (独立) $t_4 t_4$ (扩大)

不能写成 A_p, A_s 相乘的形式
 + 一个交点

loop 意义 \Rightarrow Wilson loop geometry phase

$\pi \sigma_i^z = e^{i\varphi}$ $e^{i2\varphi} = 1 \Rightarrow \varphi = 0, \pi$

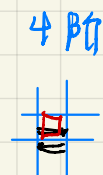
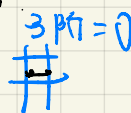
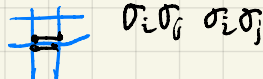
$\varphi = \varphi_1 + \varphi_2 \pmod{2}$



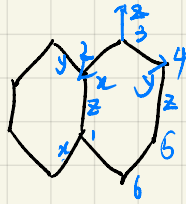
\mathbb{Z}_2 gauge theory Ising model

$Z = \text{Tr} [e^{-\beta J \sum_{\langle i,j \rangle} \sigma_i \cdot \sigma_j}]$ loop

$= \text{Tr} [1 - \beta J \sum_{\langle i,j \rangle} \sigma_i \cdot \sigma_j + \frac{(\beta J)^2}{2} (\sum_{\langle i,j \rangle} \sigma_i \cdot \sigma_j)^2 - \dots]$



Kitaev honeycomb lattice



$$H = -J_x \sum \sigma_i^x \sigma_j^x$$

$$-J_y \sum \sigma_i^y \sigma_j^y$$

$$-J_z \sum_{\langle ij \rangle} \sigma_i^z \sigma_j^z$$

$$W_p = \sigma_1^x \sigma_2^y \sigma_3^z \sigma_4^x \sigma_5^y \sigma_6^z$$

$$\textcircled{1} W_p = W_p^\dagger$$

Wilson loop

$$\textcircled{2} W_p^2 = 1$$

geometry phase

$$\textcircled{3} [W_p, W_{p'}] = 0 \quad 0/2 \uparrow \text{约束}$$

$$\textcircled{4} [W_p, H] = 0$$

$$\sigma^x = i b^x c$$

$$\sigma^y = i b^y c$$

$$\sigma^z = i b^z c$$

b, c majorana fermion

$$\begin{cases} r_i r_j = -r_i r_j & i \neq j \\ r_i^2 = 1 \end{cases}$$

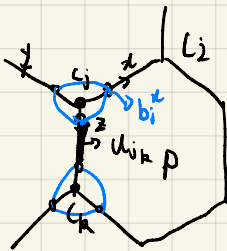
$$\sigma^x \sigma^x = i b^x c i b^x c$$

$$= (+1) b^x b^x c c = 1$$

$$\sigma^x \sigma^y \sigma^z = i \sigma^z^2 = i D$$

$$= i b^x c i b^y c i b^z c$$

$$= i b^x b^y b^z c \quad \text{约束}$$



$$\sigma_j^x = i b_j^x c_j$$

$$\sigma_j^z \sigma_k^z = i b_j^z c_j i b_k^z c_k$$

$$= b_j^z b_k^z c_j c_k$$

$$\sigma_j^x \sigma_k^x = b_j^x b_k^x c_j c_k$$

$$W_p = \prod U_{jk}$$

$$\text{e.g. } H = -\sum_{ij} t e^{-i\int_{ij} \vec{A} \cdot d\vec{l}} c_i^\dagger c_j$$

$$= -\sum_{ij} t e^{i\theta_{ij}} c_i^\dagger c_j$$

Wenn RVB

$$= \sum_{ij} U_{ij} c_i^\dagger c_j$$

$$H = \frac{i}{4} \sum_{ij} A_{ij} c_i c_j$$

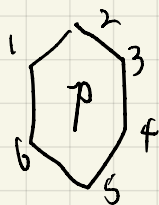
$$A_{ij} = 2i J_\alpha b_j^\alpha b_i^\alpha$$

\Downarrow

$$[b_i^\alpha b_j^\alpha, H] = 0$$

af WS. $A_{ij} = J^\alpha \Rightarrow i b_j^\alpha b_i^\alpha = 1$

$$H = \frac{1}{4} \sum J_\alpha c_i c_j$$



$$\frac{J_x}{4} c_1 c_2 + \frac{J_y}{4} c_2 c_3 + \dots$$

$$H_q = \begin{pmatrix} 0 & f_q \\ f_q^\dagger & 0 \end{pmatrix}$$

$$f_q = J_z + J_x e^{i\vec{q} \cdot \vec{R}_1} + J_y e^{i\vec{q} \cdot \vec{R}_2}$$

