

Online course on topology in condense matter

《《 A short Course On Topology Insulator》》

同调群 Nakahara ch 3. 加法群

$H_d(K, G)$
上同调群
 $H^d(K, G)$ } Stokes 定理

$$\int_{\partial V} d\omega = \int_V \omega$$

↓
等价关系 $V \sim V + \partial\sigma$
边界无边界 $\partial^2 = 0$

群的分类 $\Rightarrow H$
子群

H_d	$V \sim V + \partial\sigma$	$\partial^2 = 0$
H^d	$\omega \rightarrow \omega + d\eta$	$d^2 = 0$

目的: 出现在许多文章中.

要求: 意义.

$$H_1(T^2) = \mathbb{Z} \oplus \mathbb{Z}$$

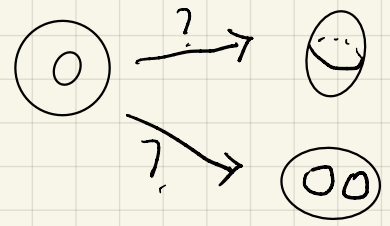
$$H_1(\text{球}) = 0$$

同位群 \Rightarrow 广泛应用 Topo bands, Topo defect

$\pi_n(X)$
 (数) 映射, (形象) 形变

观念上的变化 $H_k = e^{i\vec{k}\cdot\vec{x}} H e^{-i\vec{k}\cdot\vec{x}}$

$$H = \int_{\vec{k}} \rightarrow H_k$$



$$\begin{aligned}
 & \begin{cases} \equiv +1 \\ \dots \\ \equiv -1 \end{cases} \\
 & Q_k = U_k \begin{pmatrix} +1 & \\ & -1 \end{pmatrix} U_k^\dagger \\
 & Q_k^\dagger Q_k = U_k \begin{pmatrix} +1 & \\ & -1 \end{pmatrix} U_k^\dagger U_k \begin{pmatrix} +1 & \\ & -1 \end{pmatrix} \\
 & \quad = U_k U_k^\dagger = \mathbb{1} \\
 & Q_k \in U(N+M)
 \end{aligned}$$

\checkmark (元) $V: \mathbb{R}^3 \rightarrow \mathbb{R}^d$

群 (四要素, $*$) = $\langle G, *$

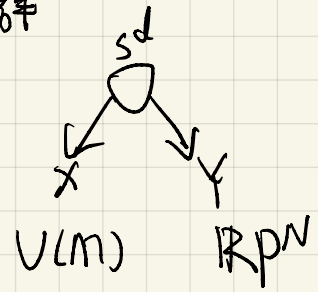
同位群 \Rightarrow 映射 $f: X \rightarrow Y$

群元: 由映射 $f: X \rightarrow Y$

定义 e
 a^{-1}
 $a*b$
 $(a*b)*c = a*(b*c)$

分类: 等价关系 $G/\sim = M$

同位群



$\pi_d(X) \cong \pi_d(Y)$, 可能 $X \simeq Y$.
 必要条件.

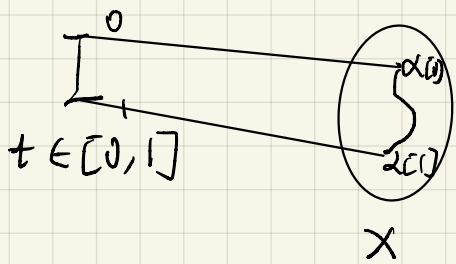
参考内容: nakahara CH 4

Veda BEC (CH1) ??

Homotopy group

Atland Simon CH 9 ??

path
路径

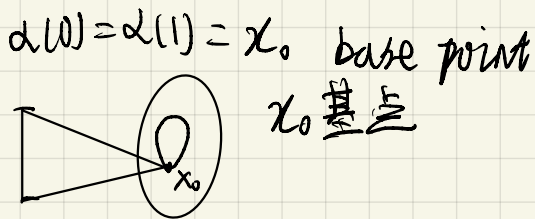


$\alpha(0)$ 可以 $\neq \alpha(1)$

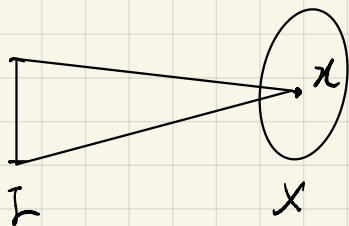
$\alpha(0) = \alpha(1)$ 闭合曲线

$\alpha: t \in [0, 1] \rightarrow \alpha(t)$ 是 X 中一条曲线

loop



constant path $(c: I \rightarrow X) \quad c(I) = x$



恒元 e .

constant loop



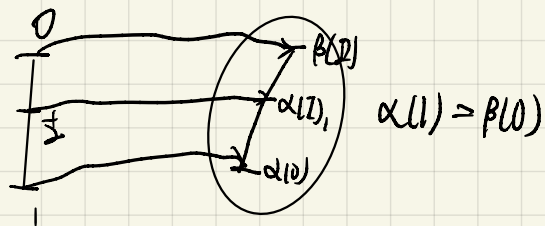
乘法. eg. $z = e^{i\theta} \in S^1 \Rightarrow z^2$

$z^{n+m} = z^n \cdot z^m$ (乘法)



$$(\alpha \# \beta) = \begin{cases} \alpha(2s) & 0 \leq s \leq \frac{1}{2} \\ \beta(2s-1) & \frac{1}{2} \leq s \leq 1 \end{cases}$$

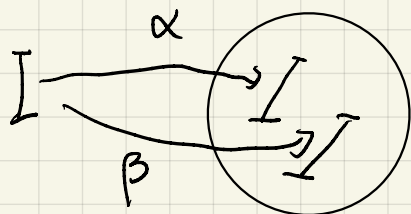
$\frac{1}{2}$ 非必要



$$\alpha^{-1}: \alpha^{-1}(s) = \alpha(1-s)$$

$$\alpha \neq \alpha^{-1} = e? \quad \alpha \neq \alpha^{-1} = \begin{cases} \alpha(2s) \\ \alpha^{-1}(2s-1) = \alpha(2-2s) \end{cases} \neq e.$$

同伦关系 Homotopy equivalence

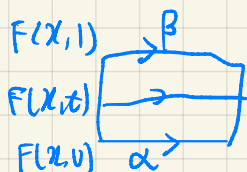


$$f, g: X \rightarrow Y$$

$f \sim g$: 连续形变

$$F(x, t) \begin{cases} F(x, 0) = f \\ F(x, 1) = g \end{cases}$$

e.g.



对 f 和 $g: X \rightarrow Y$.

$$\exists F(x, t): X \times I \rightarrow Y.$$

$$\left. \begin{array}{l} \text{使得 } F(x, 0) = f \\ F(x, 1) = g \end{array} \right\} f \sim g$$

显然 $f \sim g, g \sim h \Rightarrow g \sim h$.

同伦类

homotopy class

$$[\alpha] = \{\beta \mid \alpha \sim \beta\}$$

e.g. $[0] = \{2n\}$

$$[1] = \{2n+1\}$$

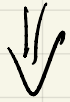
$$\mathbb{Z}_2 = \{[0], [1]\}$$

助教注: 参考陪集的概念 $[\alpha] = \{g \mid g \in \alpha H\}$.

发现 $[\alpha] * [\beta] = [\alpha * \beta]$

$$\alpha * \beta = \alpha * \beta$$

$$\begin{array}{l} \alpha \\ \beta \end{array} \begin{array}{l} \rightarrow \\ \rightarrow \end{array} \begin{array}{l} [\alpha] \\ [\beta] \end{array}$$



最终群 (同伦类)

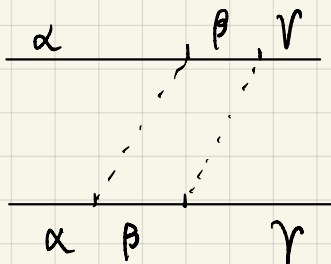
① $[\text{id}] = e$

② $[\alpha] * [\alpha] = [\alpha]$

③ $[\alpha^{-1}] * [\alpha] = [\text{id}] = e$

④ $([\alpha] * [\beta]) * [\gamma] = [\alpha] * ([\beta] * [\gamma])$

在同伦等价的意义下相等



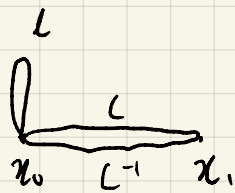
$\pi_n(X)$

原则上 $f: X \rightarrow Y$ $U(N) \rightarrow O(N)$ 过于复杂

我们关注 $f: S^d \rightarrow X$ $\pi_d(X)$

自然 $\pi_d(X) = 0 = \{[\text{id}]\}$ $\left\{ \begin{array}{l} \text{平庸} \\ \text{所有映射都等价} \end{array} \right.$

$I \rightarrow \textcircled{0}_{x_0}$ C_x base point



$$\pi_d(x, x_0) \quad C$$

$$\pi_d(x, x_1) \quad C \circ C^{-1}$$

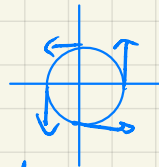
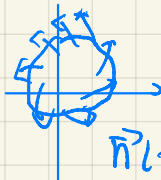
$\pi_d(X)$ ① 计算 (数学) 查表

② 应用

③ 计算 (物理) $H_k \rightarrow$ Topo number

Defects

XY model

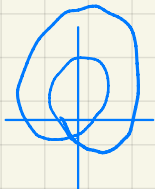
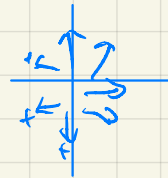


$$\vec{n}(x)$$

$$\vec{r} \int d\theta$$

$$d\theta = \vec{n} \cdot d\vec{n}$$

液晶 0 dipole



$$\frac{1}{2\pi i} \oint \frac{f(z)}{f(z)} dz$$

$$\frac{1}{2\pi i} \oint \frac{dz}{z - z_0}$$

$$\text{Gauss } \epsilon_0 \oint \vec{E} \cdot d\vec{s} = Ne$$

Qi-Wu-Zhang

$$1d \quad \frac{1}{2\pi i} \oint \frac{dz}{z}$$

$$2d \quad \frac{1}{4\pi} \oint \vec{n} \cdot (\vec{n}_x \times \vec{n}_y) dx dy$$

$$nd \quad \epsilon^{i_1 i_2 \dots i_d} n_{i_1} (\partial x_1 n_{i_2}) \dots (\partial x_{d-1} n_{i_d}) dx_1 dx_2 \dots dx_{d-1}$$