

# 计算物理作业 2

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## HW17

- ▶ 求解一维单粒子体系  $\left[-\frac{\hbar^2}{2m} \frac{d^2}{dx^2} + V_0 \sin(qx)\right] \Psi(x) = E\Psi(x)$ , 参数自取。
- ▶ 正交完备基展开:  $\Psi = \sum_n c_n \sqrt{\frac{2}{L}} \sin\left(\frac{n\pi x}{L}\right)$

基矢:  $\psi_n = \sqrt{\frac{2}{L}} \sin\left(\frac{n\pi x}{L}\right)$

矩阵元:

$$H_{nm} = \langle \psi_n | H | \psi_m \rangle = \frac{\hbar^2}{2m} \left(\frac{\pi n}{L}\right)^2 \delta_{nm} + \int_0^L V_0 \sin(qx) \frac{2}{L} \sin\left(\frac{n\pi x}{L}\right) \sin\left(\frac{m\pi x}{L}\right) dx$$

$$T_{nn}[n_-, n_-] := \frac{\hbar^2}{2m} \left(\frac{\pi n}{L}\right)^2;$$

$$V_{nm}[n_-, m_-] := \text{Integrate}\left[V_0 \frac{2 \sin[qx]}{L} \underset{\text{正弦}}{\sin\left[\frac{n\pi x}{L}\right]} \underset{\text{正弦}}{\sin\left[\frac{m\pi x}{L}\right]}, \{x, 0, L\}\right];$$

$$H = T_{nn} + V_{nm};$$

## HW18

- ▶ 两粒子系统  $H = H_0 + V$ , 单粒子部分  $H_0 = -\frac{\hbar^2}{2m} \left( \frac{d^2}{dx^2} + \frac{d^2}{dy^2} \right)$ , 相互作用部分  $V = g\delta(x - y)$ 。任选 Bose/Fermi 子一种情况求解, 并且当  $g \rightarrow 0$  和微扰结果比较。

$$\psi_n = \sqrt{\frac{2}{L}} \sin\left(\frac{n\pi x}{L}\right)$$

- ▶ Fermion

$$\text{基矢 } c_{n_1}^\dagger c_{n_2}^\dagger |0\rangle \equiv |n_1 n_2\rangle = \psi_{n_1}(x)\psi_{n_2}(y) - \psi_{n_2}(x)\psi_{n_1}(y)$$

$$H_0 \text{ 部分能量: } \frac{\hbar^2 \pi^2}{2mL^2} (n_1^2 + n_2^2)$$

相互作用部分:

$$\begin{aligned} V &= \text{FullSimplify}[(\psi[n_4, x] \psi[n_3, y] - \psi[n_3, x] \psi[n_4, y]) g \text{DiracDelta}[x - y] (\psi[n_1, x] \psi[n_2, y] - \psi[n_2, x] \psi[n_1, y])] \\ &\quad \text{[完全简化]} \quad \text{[狄拉克\delta函数]} \\ V_{nm} &= \text{Integrate}[V, \{x, 0, L\}, \{y, 0, L\}] \\ &\quad \text{[积分]} \\ &= \frac{4 g \text{DiracDelta}[x - y] \left( \sin\left[\frac{n_2 \pi x}{L}\right] \sin\left[\frac{n_1 \pi y}{L}\right] - \sin\left[\frac{n_1 \pi x}{L}\right] \sin\left[\frac{n_2 \pi y}{L}\right] \right) \left( -\sin\left[\frac{n_4 \pi x}{L}\right] \sin\left[\frac{n_3 \pi y}{L}\right] + \sin\left[\frac{n_3 \pi x}{L}\right] \sin\left[\frac{n_4 \pi y}{L}\right] \right)}{L^2} \end{aligned}$$

## HW18

### ► Boson

基矢  $a_{n_1}^\dagger a_{n_2}^\dagger |0\rangle \equiv |n_1 n_2\rangle = \psi_{n_1}(x)\psi_{n_2}(y) + \psi_{n_2}(x)\psi_{n_1}(y), \quad n_1 \neq n_2$

$\frac{1}{\sqrt{2}}(a_n^\dagger)^2 |0\rangle = \frac{2}{\sqrt{2}}\psi_n(x)\psi_n(y), \quad n_1 = n_2 = n$

$H_0$  部分能量:  $\frac{\hbar^2 \pi^2}{2mL^2}(n_1^2 + n_2^2)$

相互作用部分:

$$V = \text{FullSimplify}\left[\left(\frac{2}{\sqrt{2}} \psi[n, x] \psi[n, y]\right) g \text{DiracDelta}[x - y] \left(\frac{2}{\sqrt{2}} \psi[n, x] \psi[n, y]\right)\right]$$

完全简化      狄拉克δ函数

`Integrate[V, {x, 0, L}, Assumptions → 0 ≤ y ≤ L] /. {n → 1}`

积分      假设

`Integrate[%, {y, 0, L}, Assumptions → L > 0]`

积分      假设

Out[43]=

$$\frac{8 g \text{DiracDelta}[x - y] \text{Sin}\left[\frac{n \pi x}{L}\right]^2 \text{Sin}\left[\frac{n \pi y}{L}\right]^2}{L^2}$$

Out[44]=

$$\frac{8 g (-1 + 2 \text{HeavisideTheta}[L]) \text{HeavisideTheta}[y - L \text{HeavisideTheta}[-L]] \text{Sin}\left[\frac{\pi y}{L}\right]^4}{L^2}$$

Out[45]=

$$\frac{3 g}{L}$$

# HW18

## 相互作用部分矩阵元:

in[40]:=

```
V = FullSimplify[(ψ[n4, x] ψ[n3, y] + ψ[n3, x] ψ[n4, y]) g DiracDelta[x - y] (ψ[n1, x] ψ[n2, y] + ψ[n2, x] ψ[n1, y])]
```

完全简化

狄拉克δ函数

```
Integrate[V, {x, 0, L}, Assumptions → 0 ≤ y ≤ L] /. {n1 → 1, n2 → 2, n3 → 3, n4 → 4}
```

积分

假设

```
Integrate[%, {y, 0, L}, Assumptions → L > 0]
```

积分

假设

out[40]=

$$\frac{4 g \text{DiracDelta}[x - y] \left( \sin\left[\frac{n2 \pi x}{L}\right] \sin\left[\frac{n1 \pi y}{L}\right] + \sin\left[\frac{n1 \pi x}{L}\right] \sin\left[\frac{n2 \pi y}{L}\right] \right) \left( \sin\left[\frac{n4 \pi x}{L}\right] \sin\left[\frac{n3 \pi y}{L}\right] + \sin\left[\frac{n3 \pi x}{L}\right] \sin\left[\frac{n4 \pi y}{L}\right] \right)}{L^2}$$

in[41]=

$$\frac{16 g (-1 + 2 \text{HeavisideTheta}[L]) \text{HeavisideTheta}[y - L \text{HeavisideTheta}[-L]] \sin\left[\frac{\pi y}{L}\right] \sin\left[\frac{2 \pi y}{L}\right] \sin\left[\frac{3 \pi y}{L}\right] \sin\left[\frac{4 \pi y}{L}\right]}{L^2}$$

out[42]=

$$\frac{2 g}{L}$$

## HW19

Holstein-Primakoff(HP)变换, Spin系统和Bose系统之间的变换, 设变换形式:

$$\begin{cases} S^{\dagger} = f(n)a^{\dagger} \\ S^{-} = af(n) \\ S^z = g(n) \end{cases}$$

得到关系式:

$$\begin{cases} f^2(n) = B_1 + B_2n \\ g(n) = A + n \end{cases}$$

确定 $A, B_1, B_2$ 可以得到: 
$$\begin{cases} S_i^{\dagger} = (\sqrt{2S-n})a_i \\ S_i^{-} = a_i^{\dagger}\sqrt{2S-n} \\ S_i^z = S-n \end{cases} \text{ or } \begin{cases} S_i^{\dagger} = a_i^{\dagger}(\sqrt{2S-n}) \\ S_i^{-} = \sqrt{2S-na_i} \\ S_i^z = n-S \end{cases} \text{ 其中 } n = a_i^{\dagger}a_i$$

作业19 找到上面参数 $A, B_1, B_2$ 之间的关系

- ▶ 利用对易关系

$$[S^+, S^-] = 2S^z$$

$$[S^z, S^+] = S^+$$

$$S^2 = (S^z)^2 + \frac{1}{2} (S^+ S^- + S^- S^+) = S(S+1)$$

▶ 得到

$$f^2(n)n - f^2(n+1)(n+1) = 2g(n)$$

$$g(n) - g(n-1) = 1$$

$$g^2(n) + \frac{1}{2} [f^2(n)n + f^2(n+1)(n+1)] = S(S+1)$$

⇒

$$-2B_2n - B_1 - B_2 = 2A + 2n$$

$$A^2 + \frac{1}{2} (B_1 - 1) + (2A + B_1 - 1)n = S(S+1)$$

⇒

$$A = -S, B_1 = 1 + 2S, B_2 = -1$$

$$A = 1 + S, B_1 = -1 - 2S, B_2 = -1$$

## HW20

$$(1). \text{Schwinger Boson} \begin{cases} S^{\dagger} = a^{\dagger}b \\ S^{-} = b^{\dagger}a \\ S^z = (a^{\dagger}a - b^{\dagger}b)/2 \end{cases}$$

(a). 证明  $[S^{\dagger}, S^{-}] = 2S_z$ ; (b). 计算  $S^2$ ; (c). 证明基矢  $|S, m\rangle = \frac{(a^{\dagger})^{S+m}(b^{\dagger})^{S-m}}{\sqrt{(S+m)!(S-m)!}}|0\rangle$  是算符  $S^2, S^z$  的本征态,

对应本征值  $S(S+1), m$ , 这里  $a^{\dagger}a + b^{\dagger}b = 2S$

(2). Schwinger Fermion 同样计算(1)中的问题

(3). Dyson-Maleev 变化

$$\begin{cases} J^{\dagger} = a \\ J^{-} = a^{\dagger}(2S - n) \\ J^z = S - a^{\dagger}a \end{cases}$$

计算  $[J^{\dagger}, J^{\dagger}], J^2$

(4).  $\vec{J} = \frac{1}{2}a^{\dagger}\vec{\sigma}a$ , 证明  $\vec{J}$  和  $\vec{\sigma}$  有相同对易关系, 计算  $J^2$

► (1a)

$$\begin{aligned} [S^{\dagger}, S^{-}] &= S^{\dagger}S^{-} - S^{-}S^{\dagger} = a^{\dagger}bb^{\dagger}a - b^{\dagger}aa^{\dagger}b \\ &= a^{\dagger}abb^{\dagger} - aa^{\dagger}b^{\dagger}b \\ &= a^{\dagger}a(b^{\dagger}b + 1) - (a^{\dagger}a + 1)b^{\dagger}b = a^{\dagger}a - b^{\dagger}b \\ &= 2S^z \end{aligned}$$



## HW20

► (1b)

$$\begin{aligned}
 S^2 &= (S^z)^2 + \frac{1}{2} (S^+ S^- + S^- S^+) \\
 &= \left[ \frac{a^+ a - b^+ b}{2} \right]^2 + \frac{1}{2} (a^+ b b^+ a + b^+ a a^+ b) \\
 &= \frac{a^+ a + b^+ b}{2} \left( \frac{a^+ a + b^+ b}{2} + 1 \right) \\
 &= \frac{n_a + n_b}{2} \left( \frac{n_a + n_b}{2} + 1 \right) = S(S+1)
 \end{aligned}$$

► (1c)

$$\begin{aligned}
 |S, m\rangle &= \frac{(a^+)^{S+m} (b^+)^{S-m}}{\sqrt{(S+m)!(S-m)!}} |0\rangle = |S+m\rangle_a |S-m\rangle_b \\
 S^2 |S+m\rangle_a |S-m\rangle_b &= \frac{n_a + n_b}{2} \left( \frac{n_a + n_b}{2} + 1 \right) |S+m\rangle_a |S-m\rangle_b \\
 &= \frac{n_a + n_b}{2} \left[ \frac{1}{2} (S+m+S-m) + 1 \right] |S+m, S-m\rangle \\
 &= S(S+1) |S+m\rangle_a |S-m\rangle_b \\
 S^z |S+m\rangle_a |S-m\rangle_b &= m |S+m\rangle_a |S-m\rangle_b
 \end{aligned}$$

## HW20

► (3)

$$[J^+, J^-] = J^+ J^- - J^- J^+ = a a^\dagger (2S - n) - a^\dagger (2S - n) a = 2J^z$$

$$\begin{aligned} J^2 &= (J^z)^2 + \frac{1}{2} (J^+ J^- + J^- J^+) \\ &= (S - n)^2 + \frac{1}{2} ((n + 1)(2S - n) + n(2S - n + 1)) \\ &= S(S + 1) \end{aligned}$$

► (4) 二分量:  $\mathbf{a}^\dagger = (a_1^\dagger, a_2^\dagger)$

$$J_0 = \frac{1}{2} \mathbf{a}^\dagger \sigma_0 \mathbf{a} = \frac{1}{2} (a_1^\dagger a_1 + a_2^\dagger a_2)$$

$$J_x = \frac{1}{2} \mathbf{a}^\dagger \sigma_x \mathbf{a} = \frac{1}{2} (a_1^\dagger a_2 + a_2^\dagger a_1)$$

$$J_y = \frac{1}{2} \mathbf{a}^\dagger \sigma_y \mathbf{a} = \frac{i}{2} (-a_1^\dagger a_2 + a_2^\dagger a_1)$$

$$J_z = \frac{1}{2} \mathbf{a}^\dagger \sigma_z \mathbf{a} = \frac{1}{2} (a_1^\dagger a_1 - a_2^\dagger a_2)$$

► 得到:

$$[J_x, J_y] = iJ_z, \quad [J_y, J_z] = iJ_x, \quad [J_z, J_x] = iJ_y$$

$$\begin{aligned} J^2 &= J_x^2 + J_y^2 + J_z^2 \\ &= \frac{n_1 + n_2}{2} \left( \frac{n_1 + n_2}{2} + 1 \right) \\ &= \frac{n}{2} \left( \frac{n}{2} + 1 \right) \end{aligned}$$

## HW21

- ▶  $H = bS^\dagger + b^*S^- + b_z S^z$ , 代入 HP 变换  
 $S^\dagger = a^\dagger \sqrt{2S - a^\dagger a}$ ,  $S^- = \sqrt{2S - a^\dagger a} a$ ,  $S^z = a^\dagger a - S$ , 求解自由能。
- ▶ 考虑  $S = \frac{1}{2}$ , 则  $H = ba^\dagger \sqrt{1-n} + b^* \sqrt{1-na} + b_z(n - \frac{1}{2})$ , 基矢  $|0\rangle, |1\rangle$

$$H|0\rangle = b|1\rangle - \frac{1}{2}b_z|0\rangle$$

$$H|1\rangle = b^*|0\rangle + \frac{1}{2}b_z|1\rangle$$

$$H = \begin{pmatrix} -b_z/2 & b \\ b^* & b_z/2 \end{pmatrix}$$

能级  $E = \pm \frac{1}{2} \sqrt{4|b|^2 + |b_z|^2}$

配分函数  $Z = \sum_n e^{-\beta E_n}$

自由能  $F = -\beta^{-1} \ln Z = -\frac{\ln[2 \cosh(\frac{1}{2}\beta \sqrt{4|b|^2 + |b_z|^2})]}{\beta}$

## HW22

▶ 计算  $\sum_{nm} (\Delta a_n^\dagger b_n^\dagger + \Delta b_n^\dagger a_m^\dagger + h.c.)$  的色散关系。

▶ FT:

$$a_n = \frac{1}{\sqrt{N}} \sum_k a_k e^{ikn}, \quad b_n = \frac{1}{\sqrt{N}} \sum_k b_k e^{-ikn}$$

⇒

$$H = \Delta \sum_{k\delta} (a_k^\dagger b_k^\dagger + b_k^\dagger a_k^\dagger e^{-ik\delta} + h.c.), \quad \delta = m - n$$

$$\text{Let } \gamma_k = \sum_{\delta} e^{-ik\delta} \Rightarrow H = \Delta \sum_k [(1 + \gamma_k) a_k^\dagger b_k^\dagger + h.c.]$$

▶ Bogoliubov 变换

$$a_k = u_k \alpha_k + v_k \beta_k^\dagger$$

$$b_k = u_k \beta_k + v_k \alpha_k^\dagger$$

$$u_k^2 - v_k^2 = 1$$

对角化:

$$H = \Delta \sum_k i(1 + \gamma_k) (\alpha_k^\dagger \alpha_k + \beta_k^\dagger \beta_k + 1)$$

$$E_k = i\Delta(1 + \gamma_k)$$

## HW23

作业23  $H = E_1 a_1^\dagger a_1 + E_2 a_2^\dagger a_2 + U_1 n_1(n_1 - 1) + U_2 n_2(n_2 - 1) + J(a_1^\dagger a_2 + h.c.)$

方法一: (1). 利用Schwinger-Boson变换, 用自旋算符 $J_x, J_y, J_z$ 表示以上哈密顿量

(2). 在(1)结果上进行HP变换得到 $H(a, a^\dagger)$ , 求运动方程

(3). Josephson变换:  $a = e^{-i\theta} \sqrt{\rho}, a^\dagger = \sqrt{\rho} e^{i\theta}$

方法二:  $a_1 = e^{-i\theta_1} \sqrt{N_1}, a_2 = e^{-i\theta_2} \sqrt{N_2} \Rightarrow i\dot{a}_1 = [a_1, H], i\dot{a}_2 = [a_2, H]$

$$(1). \text{推导} \begin{cases} \dot{z} = -\sqrt{1-z^2} \sin \phi \\ \dot{\phi} = \Lambda z + \frac{z}{\sqrt{1-z^2}} \cos \phi + \Delta E \end{cases} \text{其中} \begin{cases} z = \frac{N_1 - N_2}{N_1 + N_2} \\ \phi = \theta_2 - \theta_1 \end{cases}$$

(2). 数值计算

(3). 比较两种方法

### ► Schwinger-Boson

$$\begin{cases} S^+ = a_1^\dagger a_2 \\ S^- = a_2^\dagger a_1 \\ S_z = (a_1^\dagger a_1 - a_2^\dagger a_2) / 2 \end{cases}$$

$$N = a_1^\dagger a_1 + a_2^\dagger a_2$$

$$H = S_z^2 (U_1 + U_2) + S_z [E_1 - E_2 + (U_1 - U_2)(N - 1)] + J(S^+ + S^-) \\ + \left[ (E_1 + E_2) + (U_1 + U_2) \left( \frac{N}{2} - 1 \right) \right] \frac{N}{2}$$

## HW23

▶ (2) HP 变换

$$\begin{cases} S^+ = \sqrt{2S - na} \\ S^- = a^\dagger \sqrt{2S - n} \\ S_z = S - n \end{cases}$$

运动方程:

$$\begin{aligned} i\dot{a} &= [a, H] = a(U_1 + U_2)(2n - 1 - 2S) - a[E_1 - E_2 + (U_1 - U_2)(N - 1)] \\ &\quad + J\{a^2[\sqrt{2S - (n-1)} - \sqrt{2S - (n-2)}] \\ &\quad + \sqrt{2S - n} + [\sqrt{2S - n} - \sqrt{2S - (n-1)}]n\} \\ i\dot{a}^\dagger &= [a^\dagger, H] \end{aligned}$$

▶ (3) Josephson 变换

$$\begin{cases} a = e^{-i\theta} \sqrt{\rho} \\ a^\dagger = \sqrt{\rho} e^{i\theta} \end{cases}$$

假设  $S \gg \rho$

$$\begin{aligned} \dot{\rho} &= 2\sqrt{2S\rho} \sin \theta \\ \dot{\theta} &= -[2(U_1 + U_2)S + E_1 - E_2 + (U_1 - U_2)(N - 1)] + J\sqrt{2S/\rho} \cos \theta \end{aligned}$$

## HW23

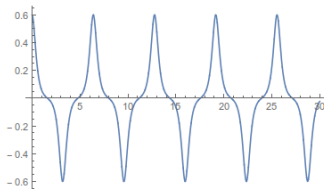
### ► 方法二 (2)

$$\text{eqs} = \left\{ z'[t] = -\sqrt{1-z[t]^2} \underset{\text{正弦}}{\text{Sin}[\phi[t]]}, \phi'[t] = \Lambda z[t] + \frac{z[t]}{\sqrt{1-z[t]^2}} \underset{\text{余弦}}{\text{Cos}[\phi[t]]} + dE, \right.$$

$$\left. z[0] = 0.6, \phi[0] = 0 \right\};$$

```
Eq = NDSolve[eqs /. {dE -> 0., Lambda -> 9.99}, {z[t], phi[t]}, {t, 0, 30}];  
[数值求解微分方程组]
```

```
Plot[Evaluate[z[t]] /. Eq, {t, 0, 30}, PlotRange -> All]  
[绘图] [计算] [绘制范围] [全部]
```

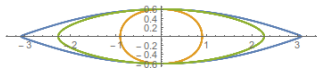


```
ParametricPlot[{Evaluate[{phi[t], z[t]} /. Eq],  
[绘制参数图] [计算]
```

```
Evaluate[{phi[t], z[t]} /. NDSolve[eqs /. {dE -> 0., Lambda -> 1}, {z[t], phi[t]}, {t, 0, 30}]],  
[计算] [数值求解微分方程组]
```

```
Evaluate[{phi[t], z[t]} /. NDSolve[eqs /. {dE -> 0., Lambda -> 8}, {z[t], phi[t]}, {t, 0, 30}]],  
[计算] [数值求解微分方程组]
```

```
{t, 0, 30}]
```





## HW24

- ▶ 对于上文 Dicke model 经典方法, 定义  $Y = (x_1, p_1, x_2, p_2)$ , 求  $\dot{Y} = AY$
- ▶ 利用

$$\dot{p}_i = -\frac{\partial H}{\partial x_i}, \quad \dot{x}_i = \frac{\partial H}{\partial p_i}$$

$$H = \frac{p_1^2}{2m} + \frac{1}{2}m\omega^2 x_1^2 + \frac{p_2^2}{2m} + \frac{1}{2}m\omega_0^2 x_2^2 + \sqrt{2}gm\sqrt{\omega\omega_0}x_1x_2 + \sqrt{2}g\frac{p_1p_2}{m\sqrt{\omega\omega_0}}$$

得到

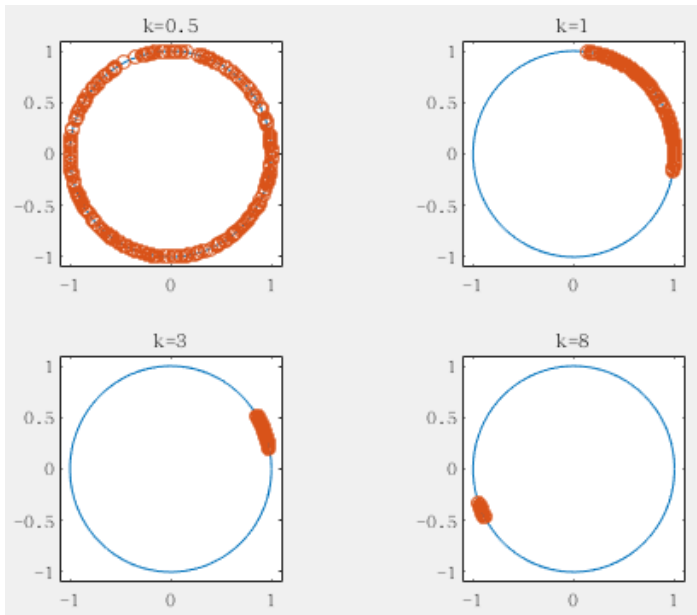
$$A = \begin{pmatrix} 0 & -m\omega^2 & 0 & -\sqrt{2}gm\sqrt{\omega\omega_0} \\ \frac{1}{m} & 0 & \frac{\sqrt{2}g}{m\sqrt{\omega\omega_0}} & 0 \\ 0 & -\sqrt{2}gm\sqrt{\omega\omega_0} & 0 & -m\omega_0 \\ \frac{\sqrt{2}g}{m\sqrt{\omega\omega_0}} & 0 & \frac{1}{m} & 0 \end{pmatrix}$$

## HW25

- ▶ Kuramoto model  $\dot{\theta}_i = \omega_i + \frac{K}{N} \sum_j^N \sin(\theta_j - \theta_i)$  数值求解,  $N = 200 \sim 500$  左右。

```
func=@(w,K,N,theta) (w+(K/N)*sum(sin(theta*ones(1,N)-ones(N,1)*theta'),1)');  
x=0:0.01:2*pi;  
T=600;  
N=300;  
K=8;  
theta0=2*pi*rand(N,1);  
w=rand(N,1);  
[t,y]=ode45(@(t,y)func(w,K,N,y),[0 T],theta0);  
subplot(2,2,4)  
plot(cos(x),sin(x),cos(y(end,:)),sin(y(end,:)), 'o')  
axis square  
axis([-1.1 1.1 -1.1 1.1])  
title('K=8')
```

## HW25



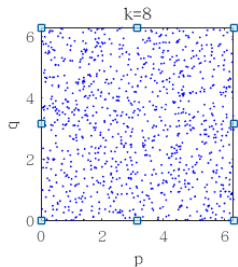
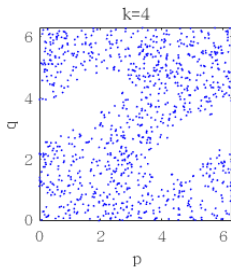
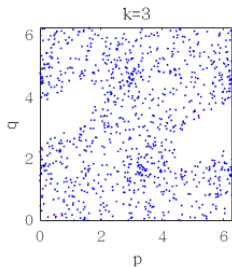
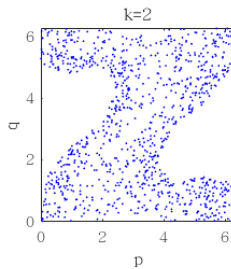
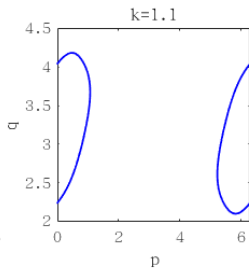
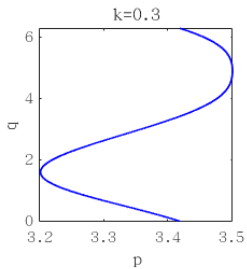
## HW26

- ▶ 求 Standard map 相图，扫描 k

$$p_{n+1}^- = p_n^- + k \sin q_n, \quad q_{n+1} = q_n + p_{n+1}^-$$

```
N=1000;
k = 8;
subplot(2,3,6)
hold on
p=2*pi*rand(1);
q=2*pi*rand(1);
for i=1:N
    p=p+k*sin(q);
    p=mod(p,2*pi);
    q=q+p;
    q=mod(q,2*pi);
    plot(p,q,'b.', 'MarkerSize',4)
end
title('k=8')
xlabel('p')
ylabel('q')
axis square
box on
```

# HW26



作业27  $H = \frac{p^2}{2} + k \cos q \sum_n [\delta(t - nT) + \delta(t - nT + T_0)]$

(1). 求出standard map方程(eq1)

(2). 画出相图(fig1)



$$\dot{p} = k \sin q \sum [\delta(t - nT) + \delta(t - nT + T_0)]$$

$$\dot{q} = p$$

时间段:  $[(n-1)T, nT - T_0], [nT - T_0, nT]$ , Let  $T = 1, 0 < T_0 < 1$

$$p_{N+1} = p_N + K_\epsilon \sin x_N; \quad p_{N+2} = p_{N+1} + K_\epsilon \sin x_{N+1}$$

$$x_{N+1} = x_N + p_{N+1}; \quad x_{N+2} = x_{N+1} + p_{N+2} \tau_\epsilon$$

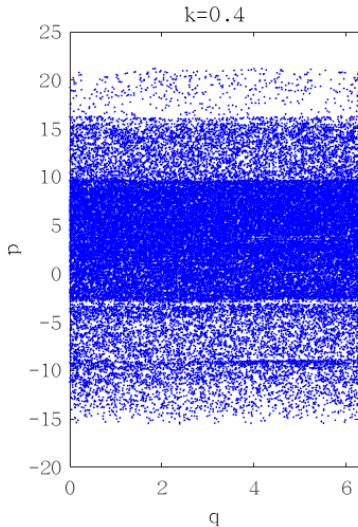
$$K_\epsilon = k\epsilon, \quad \tau_\epsilon = (T - \epsilon)/\epsilon$$

## HW27

```

N=50000;
k = 0.4;
tau = 24;
hold on
p=2*pi*rand(1);
q=2*pi*rand(1);
for i=1:N
    p=p+k*sin(q);
    q=q+p;q=mod(q,2*pi);
    p=p+k*sin(q);
    q=q+p*tau;q=mod(q,2*pi);
    Q(i)= q; P(i) = p;
end
plot(Q,P,'b.', 'MarkerSize',4)
title('k=0.4')
xlabel('q')
ylabel('p')
box on

```



## HW28

作业28 已知  $H = T(x) + V(x)$ ,  $T = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2}$ , Time-evolution equation,  $\psi(x, t + \Delta t) = e^{-i\Delta t H/\hbar} \psi(x, t)$ ,  
证明:  $e^{-i\Delta t H/\hbar} \approx e^{-i\Delta t V/(2\hbar)} e^{-i\Delta t T/\hbar} e^{-i\Delta t V/2\hbar} \psi$  holds the error ( $\mathcal{O}(\Delta t^3)$ )

$$\begin{aligned}
 e^{-i\Delta t H/\hbar} &= 1 - i\Delta t(V + T)/\hbar - \frac{\Delta t^2}{2}(V + T)^2/\hbar^2 + \frac{i\Delta t^3}{6}(V + T)^3/\hbar^3 \\
 &= 1 - \frac{i}{\hbar}(V + T)\Delta t - \frac{\Delta t^2}{2\hbar^2}(V^2 + T^2 + VT + TV) + \\
 &\quad \frac{i\Delta t^3}{6\hbar^3}(V^3 + T^3 + V^2T + TV^2 + VTV + VT^2 + TVT + T^2V) \\
 \text{right} &= \left(1 - \frac{i\Delta t}{2\hbar}V - \frac{\Delta t^2}{8\hbar^2}V^2 + \frac{i\Delta t^3}{48\hbar^3}V^3\right) \left(1 - \frac{i\Delta t}{2\hbar}T - \frac{\Delta t^2}{2\hbar^2}T^2 + \frac{i\Delta t^3}{46\hbar^3}T^3\right) \\
 &\quad \left(1 - \frac{i\Delta t}{2\hbar}V - \frac{\Delta t^2}{8\hbar^2}V^2 + \frac{i\Delta t^3}{48\hbar^3}V^3\right) \\
 &= 1 - \frac{i\Delta t}{\hbar}(V + T) - \frac{\Delta t^2}{2\hbar^2}(V^2 + T^2 + VT + TV) \\
 &\quad + \frac{i\Delta t^3}{6\hbar^3} \left( V^3 + T^3 + \frac{3}{4}(V^2T + TV^2) + \frac{3}{2}(VT^2 + T^2V + VTV) \right)
 \end{aligned}$$



## HW29

作业29 已知Time-Dependent Gross-Pitaevskii Equation

$i\hbar \frac{\partial}{\partial t} \psi(x, t) = \left[ -\frac{\hbar^2}{2m} \nabla^2 + V(x, t) + g|\psi(x, t)|^2 \right] \psi(x, t)$ , 其中  $V(x) = \frac{1}{2}m\omega^2(x^2 - a^2)$ . 数值求解基态能量和波函数。