

Differentially Private Release of Synthetic Graphs for Triangle-Motif Cut Structures

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Graphs Are Everywhere

social network

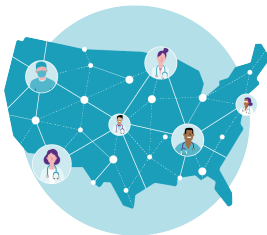
- vertex: person
- edge: friendship relation



A social network illustration (by "paixin.com")

healthcare network

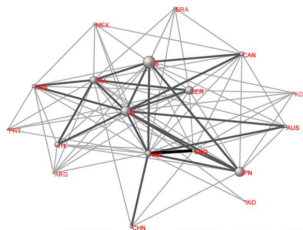
- vertex: person
- edge: doctor-patient relation



A healthcare network illustration (by "athenahealth.com")

financial network

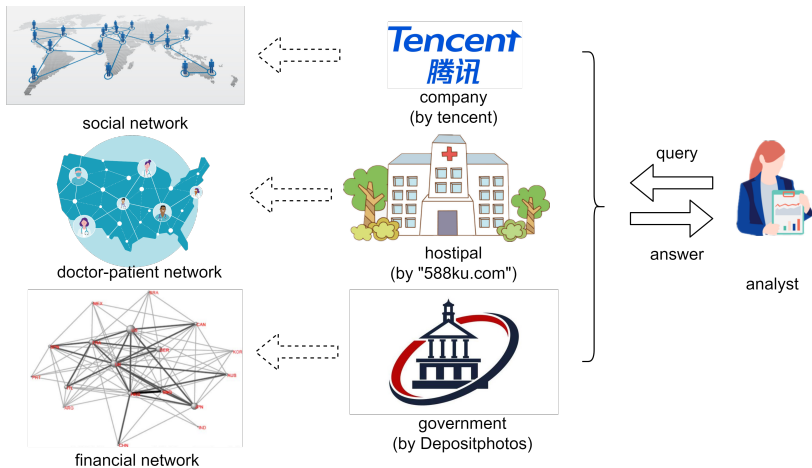
- vertex: economic entity
- edge: financial transaction-relation



The Global Financial Network in 1985 (by Haldane)

Private Release of Graph Statistics or Queries

How to protect sensitive information from an analyst who can ask questions about a particular graph?

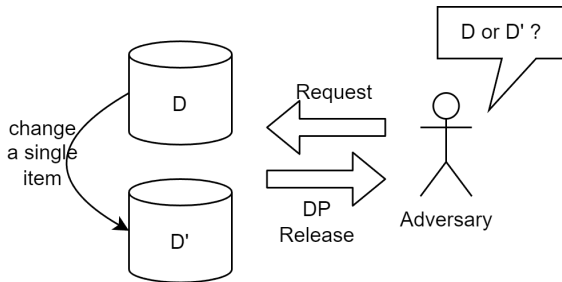


A Framework: Differential Privacy

Differential Privacy



regardless of the adversary/analyst's knowledge about the query answers,
the privacy of **individual users (or edges)** remains intact

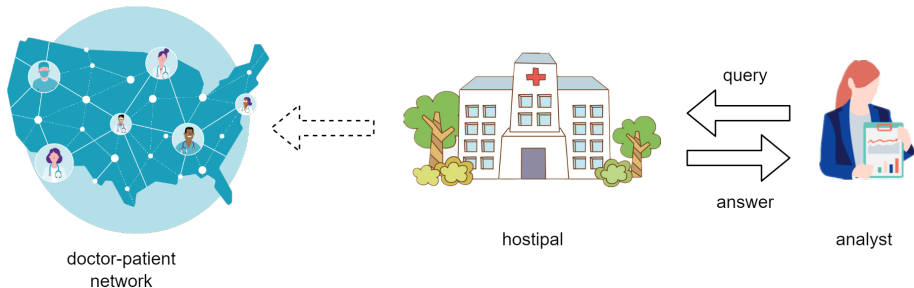


Differentially Private (DP) Release of Graph Statistics or Queries

Two approaches:

- DP query release mechanisms

- ▶ **Input:** graph+ queries
- ▶ **Output:** privacy-preserving responses to the queries
- ▶ dependent on the queries
- # triangles, degree sequence, cut queries, ...



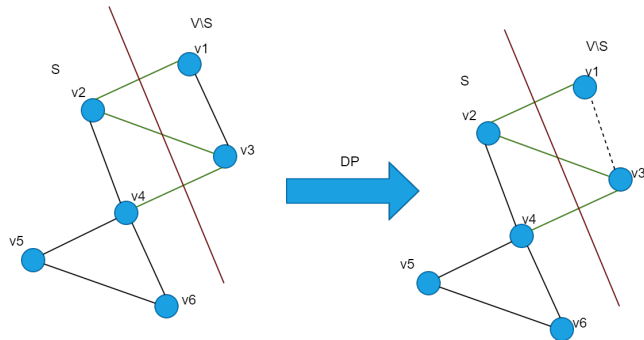
Differentially Private (DP) Release of Graph Statistics or Queries

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- DP query release mechanisms
 - ▶ **Input:** graph+ queries
 - ▶ **Output:** privacy-preserving responses to the queries
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 - # triangles, degree sequence, cut queries, ...
- DP release of a **synthetic graph**
 - ▶ **Input:** graph
 - ▶ **Output:** a graph that well approximates the property of the true one, while preserving privacy.
 - independent of queries
 - cut structure, spectral information, ...

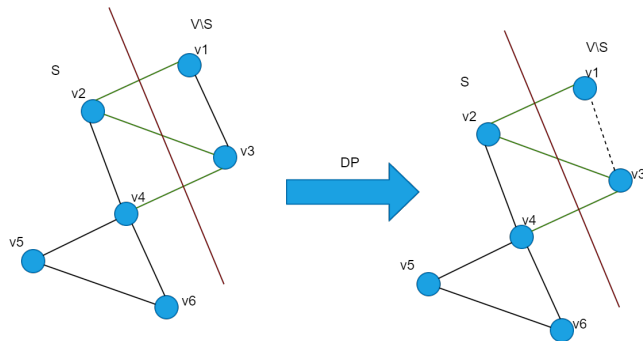
An Example: DP Synthetic Graphs for Cut Structure

- **Input:** Graph $G = (V, E)$.
- **Output:** A DP synthetic graph $G' = (V, E')$, such that for every $S \subset V$, $\text{Cut}^{(G)}(S, V \setminus S) \approx \text{Cut}^{(G')}(S, V \setminus S)$.



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- received great attention in DP community: [GRU12], [EKKL20], [LUZ24]
- upper and lower bounds $\Theta(\sqrt{mn}/\epsilon)$ [EKKL20], [LUZ24]

One Comment and One Question

Though powerful, the private synthetic graph for cut structure **fails** to capture **higher-order structure** of the graph

- higher-order structure: motifs or subgraphs (triangles, cliques, ...)
- **edge**: can be viewed as low-order structure

Question: can we privately release a graph that preserves the higher-order cut structure?

Higher-Order Structure

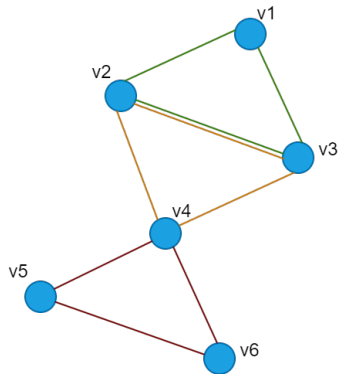
Motif

A **motif** refers to a frequently occurring subgraph within complex networks. ([MSOI+02])

- motif: triangle, wedge, cliques, ...

Applications:

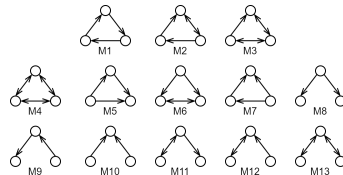
- graph clustering
- graph data visualization
- social/biological network analysis



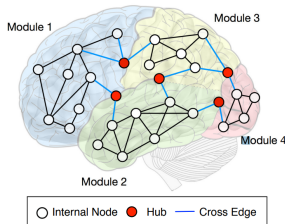
Motif

networks exhibit rich **higher-order** organizational structures ([BGL16])

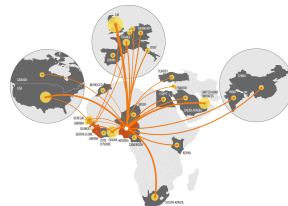
- $M_1 \sim M_7 \Rightarrow$ social networks
- $M_{13} \Rightarrow$ structural hubs in the brain
- $M_8 \sim M_{13} \Rightarrow$ air traffic networks



social network



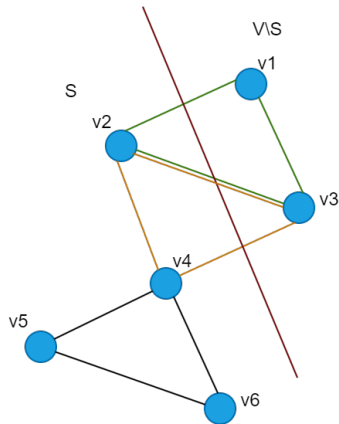
structural hubs in the brain
(by Lifang He)



air traffic networks
(by Marcelo Ferreira da Costa Gomes)

Motif Cut

The **motif size** of a cut refers to the amount of motifs crossing the cut.

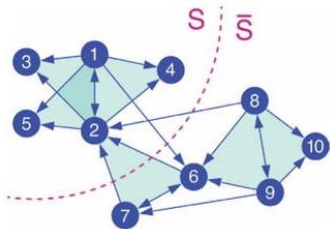


- $S = \{v2, v4, v5, v6\}$
- $\text{Cut}_{\Delta}^{(G)}(S, V \setminus S) = 2$

Applications of Motif:

1. graph clustering ([BGL16])

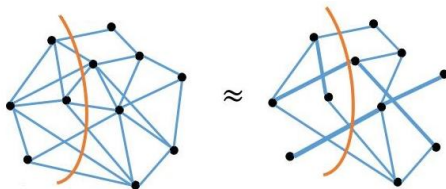
- motif cut can be used to find better clusters



(by [BGL16])

2. motif cut sparsifier ([KMSST22])

- speeding up motif-cut based graph algorithms



(by Alexandr Andoni)

The Formal Definitions and Our Problem

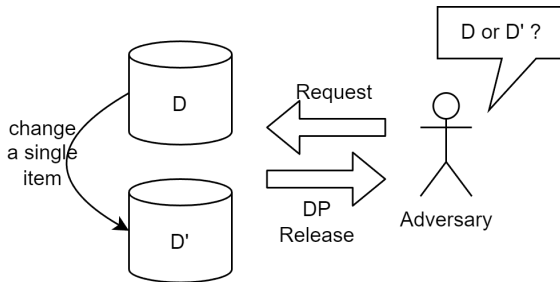
Differential Privacy

Definition $((\epsilon, \delta)$ -differential privacy)

\mathcal{M} is a $((\epsilon, \delta)$ -differentially private (DP) algorithm, if

$$\Pr[\mathcal{M}(x) \in S] \leq \Pr[\mathcal{M}(y) \in S] \cdot e^\epsilon + \delta.$$

where x and y are neighboring inputs (different in weight by 1).



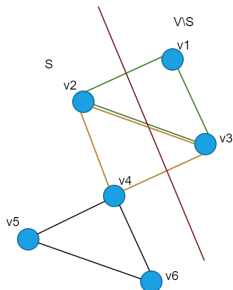
Motif Size of Cut

Given graph G , the M -**motif size** of a cut $(S, V \setminus S)$ is:

- Informally: the sum of weights of the motif M crossing $(S, V \setminus S)$
- Formally:

$$\text{Cut}_M^{(G)}(S, V \setminus S) = \sum_{I \in \mathcal{M}(G, M): I \text{ crosses } (S, V \setminus S)} w(I),$$

$w(I)$ is the product of weights of the edges of the motif instance I



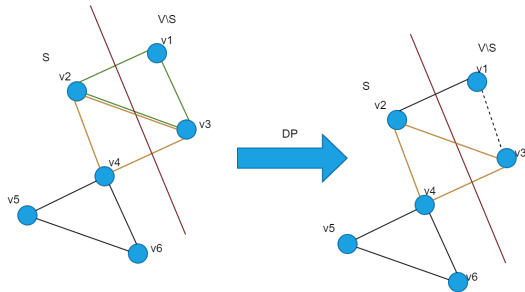
- $S = \{v_2, v_4, v_5, v_6\}$
- $\text{Cut}_{\triangle}^{(G)}(S, V \setminus S) = 2$

The Problem: Private Release of Synthetic Graphs for Motif Cut

- **Problem:** How one can efficiently release a synthetic graph that well preserves the **motif size** of all cuts, in a differentially private manner?

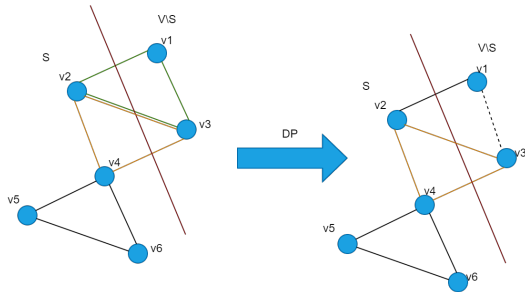
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- **Input:** A weighted graph $G = (V, E)$ and a motif M .
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- when motif is edge, it is equivalent to cut structure
- we focus on **triangle motif**

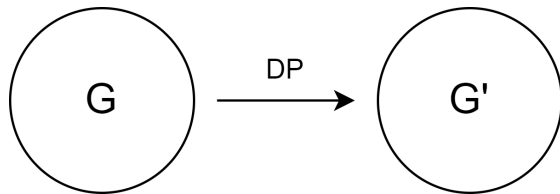
Our Results

Theorem 1 (Upper Bound)

Theorem

There exists a polynomial time (ε, δ) -DP algorithm that given an n -vertex unweighted graph G with m edges, outputs a weighted graph G' such that with probability at least $3/4$, for any cut (S, T) ,

$$|\text{Cut}_{\Delta}^{(G)}(S, T) - \text{Cut}_{\Delta}^{(G')}(S, T)| = \tilde{O}(\sqrt{mn^{\frac{3}{2}}}/\varepsilon^3).$$



for every cut
the difference is **at most**
 $\tilde{O}(\sqrt{mn^{\frac{3}{2}}}/\varepsilon^3)$

(Informal) Theorem 1 (Upper Bound)

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Remark:

- for a dense graph, the trivial approach has additive error as large as $\Theta(n^3)$.
- the edge cut case: $\Theta(\sqrt{mn})$ ([EKKL20], [UZ24])
- for weighted graph, additive error: $\tilde{O}(\sqrt{W}n^{3/2}w_{\max}^2/\varepsilon^3)$
(W : total edge weight; w_{\max} : maximum edge weight)
- can be extended to other 3-vertex motifs (e.g., wedges)

(Informal) Theorem 2 (Lower Bound)

Theorem

If an (ϵ, δ) -DP algorithm \mathcal{M} answers the triangle-motif size queries of all (S, T) -cut about G up to an additive error α with probability at least $3/4$, then $\alpha \geq \Omega(\frac{m^2}{\epsilon \cdot n^{3/2}})$

Remark:

- our algorithm is **nearly optimal** for unweighted dense graphs when $m = \Theta(n^2)$
 - ▶ upper bound: $\tilde{O}(\sqrt{m}n^{3/2}/\epsilon^3) = \tilde{O}(n^{5/2}/\epsilon^3)$
 - ▶ lower bound: $\Omega(\frac{m^2}{\epsilon \cdot n^{3/2}}) = \Omega(n^{5/2}/\epsilon)$
- for K_h motifs, lower bound: $\Omega\left(\frac{m^{(h-1)^2/2}}{\epsilon \cdot n^{h^2-3h+3/2}}\right)$.

Tempting Approaches

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- utilize the motif cut sparsifier algorithm ([KMSST22]) and add some noise
- **Failed Reason:** sampling on existing edges and never outputting non-edges poses obstacle for DP

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- **However:** we do not know how to give a hypergraph cut release algorithm

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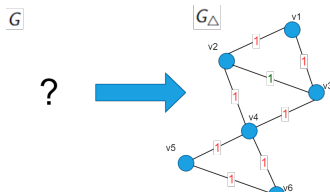
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Approach 2:

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- However:** we do not know how to give a hypergraph cut release algorithm

Approach 3:

- convert to a triangle-motif weighted graph and apply a private edge cut release algorithm
- However:** the resulting graph may not correspond to a triangle-motif weighted graph



An Inherent Difficulty

- **non-linearity**: for two graphs $G_1 = (V, E_1)$, $G_2 = (V, E_2)$, the following is **NOT** true

$$\text{Cut}_{\Delta}^{(G_1)}(S, V \setminus S) + \text{Cut}_{\Delta}^{(G_2)}(S, V \setminus S) = \text{Cut}_{\Delta}^{(G_1+G_2)}(S, V \setminus S)$$

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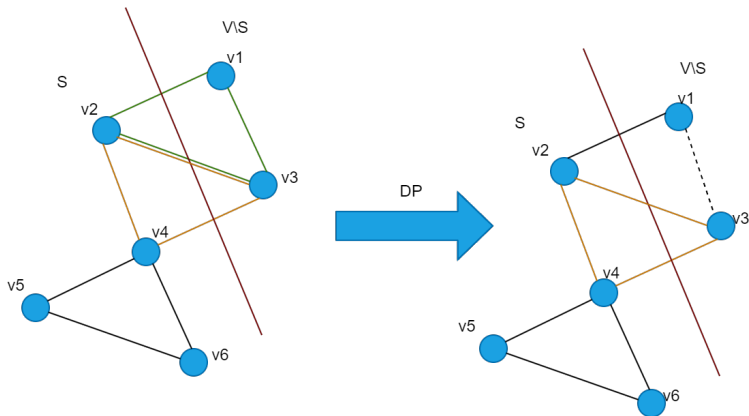
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- This is in sharp contrast with the edge case

Our Approach

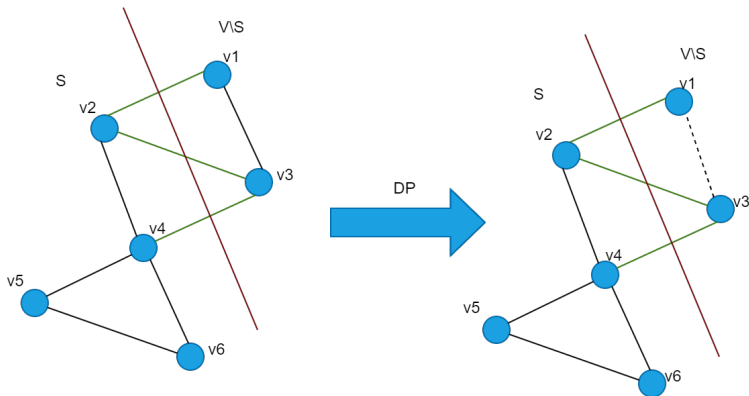
Recall: Our Problem

Given \overline{G} with m edges, the algorithm tries to privately find a synthetic graph G , which approximates the **triangle-motif cut** of \overline{G} .



Recall: The [EKKL20] Approach for Edge Cuts

Given \overline{G} with m edges, the algorithm tries to privately find a synthetic graph G , which approximates the **edge cut** of \overline{G} .



Recall: The [EKKL20] Approach for Edge Cuts

The cut difference in \overline{G} and G , can be bounded by the **SDP**:

$$\max_{\mathbf{X} \in \mathcal{D}} \left\{ \begin{pmatrix} \mathbf{0} & \mathbf{A} - \overline{\mathbf{A}} \\ \mathbf{A} - \overline{\mathbf{A}} & \mathbf{0} \end{pmatrix} \bullet \mathbf{X} \right\}$$

where $\mathcal{D} = \{ \mathbf{X} \in \mathbb{R}^{2n} : \mathbf{X} \text{ is sym.}, \mathbf{X} \succeq \frac{1}{n} \mathbf{I}_{2n}, \text{ and } \mathbf{X}_{ii} = 1 \text{ for } \forall i \}$

$$\max_{\mathbf{x}, \mathbf{y} \in \{0,1\}^n} \mathbf{x}^T \mathbf{A} \mathbf{y}$$

\Downarrow

$$\max_{\|\mathbf{u}_i\|=\|\mathbf{v}_i\|=1} \sum_{i,j} A_{i,j} \mathbf{u}_i \mathbf{v}_j$$

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$$\max_{\mathbf{X} \in \mathcal{D}} \left\{ \begin{pmatrix} \mathbf{0} & \mathbf{A} - \overline{\mathbf{A}} \\ \mathbf{A} - \overline{\mathbf{A}} & \mathbf{0} \end{pmatrix} \bullet \mathbf{X} \right\}$$

Recall: The [EKKL20] Approach for Edge Cuts

To preserve differential privacy, add **regularizer** $\lambda \log \det(\mathbf{X})$.

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\Rightarrow Try to solve the following **optimization problem**:

$$\min_{\mathbf{w} \in \mathcal{X}'} \max_{\mathbf{X} \in \mathcal{D}} \left\{ \begin{pmatrix} \mathbf{0} & \mathbf{A} - \bar{\mathbf{A}} \\ \mathbf{A} - \bar{\mathbf{A}} & \mathbf{0} \end{pmatrix} \bullet \mathbf{X} + \lambda \log \det(\mathbf{X}) \right\}$$

where the total weight of G is m (privately released).

Recall: The [EKKL20] Approach for Edge Cuts

The objective function $f(\mathbf{w})$ is **convex**, optimize it by **stochastic mirror descent**:

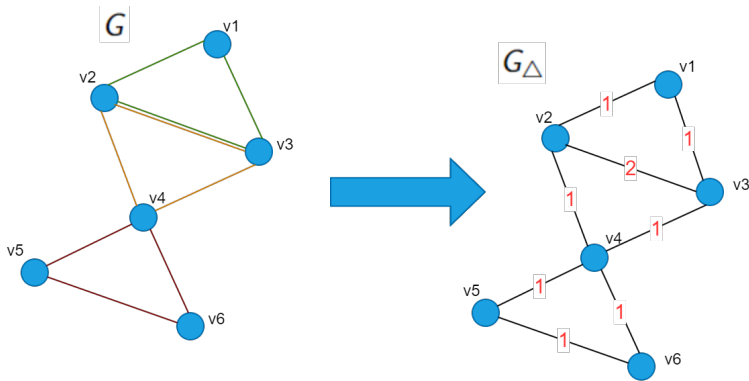
For T iterations:

- Privately release the gradient of $f(\mathbf{w})$: g_e
- Mirror descent step: $\mathbf{w}_e^{(t+1)} = m \frac{\mathbf{w}_e^{(t)} \exp(-\eta g_e^{(t)})}{\sum_e \mathbf{w}_e^{(t)} \exp(-\eta g_e^{(t)})}$

A Tool: Motif Weighted Graph

Given graph G and motif M , one can compute a **triangle-motif weighted** graph G_{Δ} with a weight vector \mathbf{w}_{Δ}

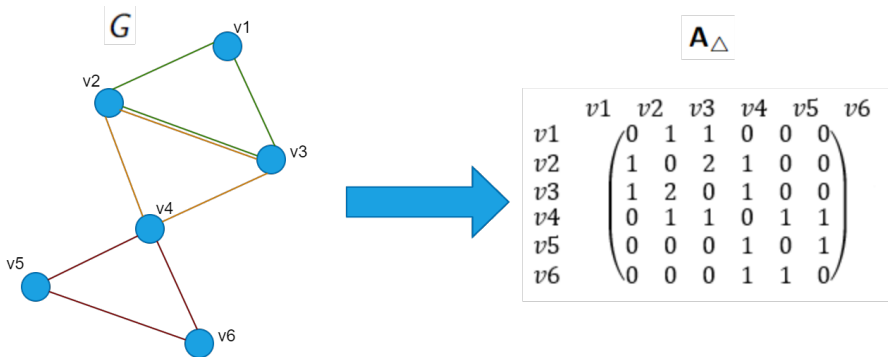
$\Rightarrow \mathbf{w}_{\Delta}(i,j)$ denotes the amount of triangles containing i,j simultaneously



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A Useful Equation

Lemma ([BGL16])

$$\text{Cut}_{\Delta}^{(G)}(S, V \setminus S) = \frac{1}{2} \text{Cut}^{(G_{\Delta})}(S, V \setminus S)$$

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Cor:(considering edge cut in G_{Δ})

The maximum triangle-motif size cut difference in \overline{G} and G , can be bounded by the following SDP up to a constant factor:

$$\max_{\mathbf{X} \in \mathcal{D}} \left\{ \begin{pmatrix} \mathbf{0} & \mathbf{A}_{\Delta} - \overline{\mathbf{A}}_{\Delta} \\ \mathbf{A}_{\Delta} - \overline{\mathbf{A}}_{\Delta} & \mathbf{0} \end{pmatrix} \bullet \mathbf{X} \right\}$$

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Note: We should optimize it w.r.t. \mathbf{w} instead of \mathbf{w}_{Δ} ; o.w. we can't convert it back to a graph.

Overview of Algorithm

- The objective function **with respect to \mathbf{w}** is **not convex**, we add a convexity regularizer $C_2 n \sum_{e \in \binom{V}{2}} (\mathbf{w}_e - \bar{\mathbf{w}}_e)^2$.
- To bound the error, we additionally require \mathbf{w} to satisfy $\mathbf{w}_e \leq C_1$. (For weighted graph, here is $\mathbf{w}_e \leq C_1 w_{\max}$)
- i.e. $\mathcal{X} = \{\mathbf{w} \in \mathbb{R}_+^{\binom{V}{2}} : \sum_{e \in \binom{V}{2}} \mathbf{w}_e = W, \mathbf{w}_e \leq C_1 \cdot w_{\max}\}$

Overview of Algorithm

Solve the following **optimization problem**:

$$\min_{\mathbf{w} \in \mathcal{X}} \max_{\mathbf{X} \in \mathcal{D}} \left\{ \begin{pmatrix} \mathbf{0} & \mathbf{A}_\Delta - \bar{\mathbf{A}}_\Delta \\ \mathbf{A}_\Delta - \bar{\mathbf{A}}_\Delta & \mathbf{0} \end{pmatrix} \bullet \mathbf{X} + \lambda \log \det(\mathbf{X}) + C_2 n \sum_{e \in \binom{V}{2}} (\mathbf{w}_e - \bar{\mathbf{w}}_e)^2 \right\}$$

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- optimize it by **stochastic mirror descent**
- the resulting graph is defined by the weight \mathbf{w}

Overview of Analysis

Trouble: Since we require \mathbf{w} to satisfy $\mathbf{w}_e \leq C_1$, the previous mirror descent step becomes invalid.

Solution:(Greedy: find the nearest solution to the primal)

- Sort the entries e by the decreasing order of $\mathbf{w}_e^{(t)} \exp(-\eta \mathbf{g}_e^{(t)})$.
- Try assign them proportional to $\mathbf{w}_e^{(t)} \exp(-\eta \mathbf{g}_e^{(t)})$.
- If there are ones larger than C_1 , truncated.

Correctness: Proved by KKT Conditions

$$\begin{array}{cccc}
 \boxed{C_1} & \boxed{C_1} & \boxed{C_1} & \boxed{C_1} \\
 \wedge & \wedge & \vee & \vee \\
 \mathbf{w}_1 \exp(-\eta \mathbf{g}_1) \geq \mathbf{w}_2 \exp(-\eta \mathbf{g}_2) \geq \mathbf{w}_3 \exp(-\eta \mathbf{g}_3) \geq \dots \geq \mathbf{w}_m \exp(-\eta \mathbf{g}_m) \\
 \Downarrow = & \Downarrow = & \Downarrow \propto & \Downarrow \propto \\
 \boxed{C_1} & \boxed{C_1} & \boxed{\mathbf{w}_3 \exp(-\eta \mathbf{g}_3)} & \boxed{\mathbf{w}_m \exp(-\eta \mathbf{g}_m)} \\
 \underbrace{\hspace{10em}} & & \underbrace{\hspace{10em}} \\
 \boxed{2C_1} & & \boxed{\sum_e \mathbf{w}_e - 2C_1}
 \end{array}$$

Overview of Analysis

Privacy:

- The privacy loss per iteration $\approx O(\frac{n}{\lambda})$
- Total privacy loss after T iterations $\approx O(\frac{n\sqrt{T}}{\lambda})$
 \Rightarrow run $T \approx \frac{\lambda^2}{n^2}$ steps to achieve differential privacy

Overview of Analysis

Privacy:

- The privacy loss per iteration $\approx O(\frac{n}{\lambda})$
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Utilization:

- The cut distance to the original graph $\overline{G} \approx O(\frac{mn}{\sqrt{T}} + \lambda n)$
- Choose $T \approx \sqrt{\frac{m}{n}} \Rightarrow$ the additive error $\approx O(\sqrt{mn}n^{3/2})$

The Lower Bound

Overview of Lower Bound

We employ the generalized **discrepancy** of 3-colorings of h -uniform hypergraphs.

Definition

Let \mathbf{B} be a 0/1 matrix with $\binom{n}{3}$ columns and $\mathcal{C} \subseteq \{-1, 0, 1\}^{\binom{n}{3}}$ be the set of allowed K_3 colorings. Then

$$\text{disc}_{\mathcal{C}}(\mathbf{B}) = \min\{\|\mathbf{B}\chi\|_{\infty} : \chi \in \mathcal{C}\}$$

Remark:

- If a mechanism is equivalent to compute some $\mathbf{B}\mathbf{x}$ with input \mathbf{x} , then $\text{disc}_{\mathcal{C}}(\mathbf{B})$ somehow measures the difference between the output with **neighboring inputs**.

Overview of Lower Bound

Definition

Construct a matrix \mathbf{A} with $\binom{n}{3}$ columns:

$$\mathbf{A}_{(S,T),I} = \begin{cases} 1 & \text{if } I \in (S \times T) \\ 0 & \text{otherwise} \end{cases}$$

Remark:

- \mathbf{A} is fixed and does not depend on G .
- Let $\mathbf{x}_{K_3} \in \{0, 1\}^{\binom{n}{3}}$ be the indicator vector of K_3 in G . Then

$$(\mathbf{A}\mathbf{x}_{K_3})_{S,T} = \text{cut}_{K_3}^{(G)}(S, T)$$

- $\mathbf{A}\mathbf{x}_{K_3}$ somehow measures the difference of motif size between neighboring graphs.

Overview of Lower Bound

Lemma ((Informal) discrepancy lower bound)

Given parameters σ, γ , let $\mathcal{C}_{\sigma, \gamma}$ be the set of all vectors $\chi = \mathbf{x}_{K_3} - \mathbf{x}'_{K_3}$ where \mathbf{x}, \mathbf{x}' are the indicator vector of edges of graphs satisfying some conditions.

$$\text{disc}_{\mathcal{C}_{\sigma, \gamma}}(\mathbf{A}) \geq \Omega(\sigma \cdot \gamma^2 n^{5/2}).$$

Overview of Lower Bound

Lemma

If \mathcal{M} is a mechanism for the motif size of all cuts that outputs \mathbf{y} with the input \mathbf{x} , i.e., $\mathbf{y} = \mathcal{M}(\mathbf{x})$, s.t.

$$\|\mathbf{y} - \mathbf{A} \cdot \mathbf{x}_{K_3}\|_{\infty} \leq \frac{1}{2} \text{disc}_{\mathcal{C}_{\sigma, \gamma}}(\mathbf{A}).$$

Then there exists a deterministic algorithm \mathcal{A} s.t.

$$\|\mathcal{A}(\mathbf{y}) - \mathbf{x}\|_1 \leq \sigma \gamma n^2.$$

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Remark:

- We can approximately **recover** the input graph if the output of a DP mechanism is too close to the accurate value.
 \Rightarrow The mechanism **can't be private**.

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- The lower bound generalizes to any K_h -motif cut.

Conclusion

Summary: Our Results

- The **first** (ϵ, δ) -DP mechanism:
 - ▶ Release a synthetic graph that approximate the triangle-motif cut structures
 - ▶ Additive error: $\tilde{O}(\sqrt{m}n^{3/2}/\epsilon^3)$
 - ▶ Our algorithm generalizes to **weighted graphs**
 - A lower bound of error: $\Omega(m^2/(n^{3/2} \cdot \epsilon))$
 - ▶ Our lower bound extends to any K_h -**motif cut**
- ⇒ **Nearly optimal** for unweighted dense graphs

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Thanks!