

$$\frac{1}{2\pi a} e^{-i\Phi(x+\varepsilon)} e^{i\Phi(x)} \sim \omega \cdot \frac{1}{2\pi a} e^{-i\Phi(x+\varepsilon) + i\Phi(x)}$$

$$\Rightarrow f(x) \sim \frac{1}{2\pi a} e^{-i\Phi(x+\varepsilon) + i\Phi(x)} \cdot \omega - \omega$$

$$\sim \frac{1}{2\pi a} e^{-i \frac{\partial \Phi}{\partial x} \varepsilon} \omega - \omega$$

$$\sim \frac{1}{2\pi a} \left( 1 - i \frac{\partial \Phi}{\partial x} \varepsilon + \frac{(-i)^2}{2} \left( \frac{\partial \Phi}{\partial x} \right)^2 \varepsilon^2 \dots \right) \omega - \omega$$

if canceled &  $a = \varepsilon$

$$\sim -\frac{i}{2\pi} \frac{\partial \Phi}{\partial x} + \dots$$

i.e.  $\psi^\dagger(x) \psi(x) \sim \partial_x \Phi$

high-order  $\psi^\dagger(x) \partial_x \psi(x) \sim (\partial_x \Phi)^2$

Review: why  $\psi = \frac{1}{\sqrt{2\pi a}} e^{i\Phi}$  is right?

1)  $\{\psi, \psi^\dagger\} = 0$

2) Hilbert space:  $e^{i\Phi} |N\rangle_0 \in \mathcal{H}_N$

3)  $Z_F = Z_B$

4)  $\{\psi(x), \psi^\dagger(y)\} = \delta(x-y)$

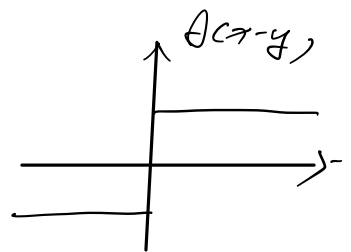
5) 关联函数  $\langle \psi(x) \psi^\dagger(y) \rangle = \frac{1}{2\pi a} \langle e^{-i\Phi(x)} e^{i\Phi(y)} \rangle$

$\rightarrow \Phi^\dagger(x) = \Phi(x)$

forsee:  $[\Phi(x), \Phi(y)] = \ln \frac{x-y-ia}{y-x-ia}$

$\sim [\Phi_+(x), \Phi_-(y)] = \ln(x-y-ia)$

$[\Phi_+(y), \Phi_-(x)] = \ln(y-x-ia)$



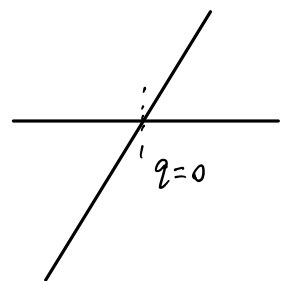
4.25.

Aim 1) 关联函数相同

2)  $[\Phi(x), \Phi(y)]$  表达式.

$$\langle \psi^\dagger(x) \psi(y) \rangle = \frac{1}{L} \sum_q e^{-iq(x-y)} \langle n | C_q^\dagger C_q | n \rangle$$

$$= \frac{1}{L} \sum_{q \neq 0} e^{-iq(x-y) + aq}, \quad \int_{-\infty}^0 e^{Aq} dq \sim \frac{1}{A}$$



$$= \frac{1}{2\pi} \int_{-\infty}^0 dq e^{[a-ic(x-y)]q}$$

$$= \frac{1}{2\pi} \frac{1}{a-ic(x-y)}$$

$$= \frac{1}{2\pi a} \langle e^{-i\phi(x)} e^{i\phi(y)} \rangle$$

$$= \frac{1}{2\pi a} e^k, \quad e^k = \frac{ia}{x-y+ia}$$

联想:  $(\partial_x^2 + \partial_y^2) \phi = \delta^2(x) \Rightarrow \phi \sim \frac{1}{2\pi} \ln r$ , 下由  $\psi = \sqrt{\frac{F}{2\pi a}} e^{i\phi}$  推广之.

$$\Phi = i \sum_{q>0} \sqrt{\frac{2\pi}{Lq}} (e^{-iq \cdot x} b_q^\dagger + e^{iq \cdot x} b_q)$$

Remarks:  $x \sim a + it$

$$p \sim ic(a-t)$$

$$\rightarrow p \sim \frac{\partial \Phi}{\partial x} \sim \sum_{q>0} p_q e^{-iq \cdot x} + p_q^\dagger e^{iq \cdot x}$$

$$\text{求 } [\Phi(x), \Phi(y)] = \sum_{q>0} \frac{2\pi}{Lq} [e^{-iq \cdot x} b_q^\dagger + e^{iq \cdot x} b_q, e^{-iq \cdot y} b_q^\dagger + e^{iq \cdot y} b_q]$$

$$= -\frac{2\pi}{L} \sum_{q>0} \left( \frac{1}{q} e^{-iq \cdot (x-y)} - aq - \frac{1}{q} e^{iq \cdot (x-y)} - aq \right) \text{ 因子}$$

①  $q = n \cdot \frac{2\pi}{L}$     ② 求和上下限

$$\text{③} = - \int_0^{+\infty} dq \cdot \frac{1}{q} (e^{-iq \cdot (x-y)} - aq - e^{iq \cdot (x-y)} - aq)$$

$$= \text{mma} \dots$$

$$\text{①} = - \sum_{n \neq 1} \frac{1}{n} (e^{(-ic(x-y)-a) \frac{2\pi}{L} n} - e^{(ic(x-y)-a) \frac{2\pi}{L} n})$$

Identity:  $\ln(1-x) = - \sum_{n \neq 1} \frac{1}{n} x^n$

$$= \ln [1 - e^{\frac{2\pi}{L} (-ic(x-y)-a)}] - \ln [1 - e^{\frac{2\pi}{L} (ic(x-y)-a)}]$$

$$\stackrel{2 \times}{=} \ln \left[ \frac{2\pi}{L} (ic(x-y)+a) \right] - \ln \left[ \frac{2\pi}{L} (ic(y-x)+a) \right]$$

$$= \ln \frac{x-y-ia}{y-x-ia} \rightarrow i\pi [\Theta(x-y) - \Theta(y-x)]$$

$$\Leftrightarrow [\Phi_+(x), \Phi_-(y)] = \ln(x-y-ia)$$

另有其无关联函数

$$\begin{aligned} & \frac{1}{2\pi a} \langle e^{-i\Phi(x)} e^{i\Phi(y)} \rangle \\ &= \frac{1}{2\pi a} \langle 0 | e^{-i(\Phi_+(x) + \Phi_-(x))} e^{i(\Phi_+(y) + \Phi_-(y))} | 0 \rangle \\ &= \frac{1}{2\pi a} \langle 0 | e^{-i\Phi(x) + i\Phi(y) + \frac{1}{2}[\Phi(x), \Phi(y)]} | 0 \rangle \\ &= \frac{1}{2\pi a} e^{\frac{1}{2}[\Phi(x), \Phi(y)]} \langle 0 | e^{-i\Phi(x) + i\Phi(y)} | 0 \rangle \\ &= \frac{1}{2\pi a} e^{\frac{1}{2}[\Phi(x), \Phi(y)]} e^{-\frac{1}{2}[A_+, A_-]} \\ &\equiv \frac{1}{2\pi a} e^k \end{aligned}$$

Normal ordering:  $:A: = A - \langle 0 | A | 0 \rangle$

or  $:e^\Phi: = e^{\Phi_+} e^{\Phi_-}$

$\Rightarrow \langle :e^\Phi: \rangle = \langle 0 | e^{\Phi_+} e^{\Phi_-} | 0 \rangle = 1$

$$\begin{aligned} e^A &= e^{A_+ + A_-} \\ &= e^{A_+} e^{A_-} e^{-\frac{1}{2}[A_+, A_-]} \end{aligned}$$

$$\begin{cases} A_+ = -i\Phi_+(x) + i\Phi_+(y) \\ A_- = -i\Phi_-(x) + i\Phi_-(y) \end{cases}$$

$$\begin{aligned} k &= \frac{1}{2}[\Phi(x), \Phi(y)] - \frac{1}{2}[A_+, A_-] \\ &= \frac{1}{2}[\Phi(x), \Phi(y)] + \frac{1}{2}[\Phi_+(x) - \Phi_+(y), \Phi_-(x) - \Phi_-(y)], [\Phi_+(x), \Phi_-(y)] = \ln(x-y-ia) \\ &= \frac{1}{2} \left\{ \ln \frac{x-y-ia}{y-x-ia} + 2 \ln(-ia) - \ln(x-y-ia) - \ln(y-x-ia) \right\}, [\Phi_+(x), \Phi_-(x)] = \ln(-ia) \\ &= \ln(-ia) - \ln(y-x-ia) = \ln \frac{ia}{x-y+ia} \implies \text{与上一步结果相同} \end{aligned}$$

then,  $\frac{1}{2\pi a} e^k = \frac{1}{2\pi a} e^{\ln \frac{ia}{x-y+ia}} = \frac{i}{2\pi} \frac{1}{x-y+ia} = \langle \psi^\dagger(x) \psi(y) \rangle$

Similarly,  $\langle \psi(x) \psi(y) \rangle \propto (x-y-ia) \dots$

then  $\langle \{ \psi(x), \psi(y) \} \rangle \propto -2ia \rightarrow 0$ .

现有  $\langle \psi^\dagger(x) \psi(y) \rangle = \frac{i}{2\pi} \frac{1}{x-y+ia}$ ,

同理  $\langle \psi(y) \psi^\dagger(x) \rangle = \frac{i}{2\pi} \frac{1}{y-x+ia}$

则  $\langle \{ \psi(y), \psi^\dagger(x) \} \rangle = \delta(x-y)$

W-D identity:

$= \frac{i}{2\pi} \left( \frac{1}{y-x+ia} + \frac{1}{x-y+ia} \right)$ , 有  $\frac{1}{x-ia} = P \frac{1}{x} + i\pi \delta(x)$

$= \frac{i}{2\pi} [P \frac{1}{y-x} - i\pi \delta(y-x) + P \frac{1}{x-y} - i\pi \delta(x-y)]$   
 $= \delta(x-y)$

即采用  $\psi(x) = \frac{F}{\sqrt{2\pi a}} e^{i\Phi(x)}$  可得 Fermionic 对易关系.

Question:  $H = \psi^\dagger \left( -\frac{\hbar^2}{2m} \nabla^2 - \mu \right) \psi + V \text{int}$

$\mathcal{L} = \frac{1}{2} (\partial\phi)^2 + A \cos\phi$

$\rho = \sum_n C_n^\dagger C_{n+q}$   
near  $\mu$ .

cos 中 如何得到?

Model: XXZ model

$$H = -J \sum_i (c_{i+1}^\dagger c_i + c_i^\dagger c_{i+1}) + \Delta \sum_i c_i^\dagger c_{i+1}^\dagger c_i c_{i+1}$$

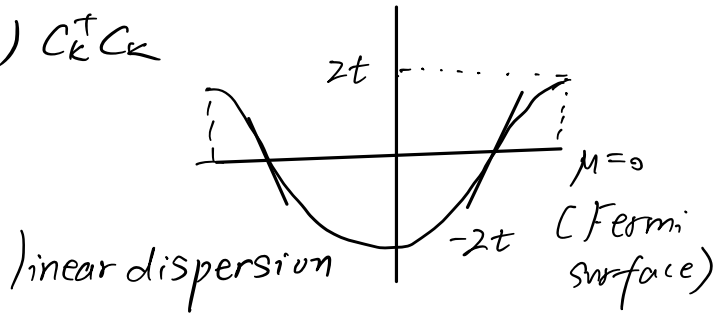
Jordan-Wigner Transformation

$$H = -t \sum_i (C_i^\dagger C_{i+1} + h.c.) + \mu C_i^\dagger C_i + U C_i^\dagger C_i C_{i+1}^\dagger C_{i+1}$$

$$H_0 \rightarrow H_{0,k} = (-2t \cos ka + \mu) C_k^\dagger C_k$$

$$H_0 = V_F \psi_R^\dagger (-i \frac{\partial}{\partial x}) \psi_R - V_F \psi_L^\dagger (-i \frac{\partial}{\partial x}) \psi_L$$

F-trans  $\sim V_F k C_k^\dagger C_k - V_F k d_k^\dagger d_k$



$$\mathcal{L} = \frac{1}{2} [(\partial_t \psi_R)^2 - V_F^2 (\partial_x \psi_R)^2] + \frac{1}{2} [(\partial_t \psi_L)^2 - V_F^2 (\partial_x \psi_L)^2]$$

$$(-2t \cos ka)' = 2at \sin ka \mid ka = \pm \frac{\pi}{2} = \pm 2at = \pm V_F$$

How to achieve this?  $\sum_i C_i^\dagger C_{i+1} \sim \int dx \psi^\dagger (\frac{\partial}{\partial x})^2 \psi$

choose  $C_i \sim \psi(x=ia)$  then  $\sum_i C_i^\dagger C_i = \int \psi^\dagger(x) \psi(x) dx$

coeff:  $C_i = \sqrt{a} \psi(x=ia)$

$$\Rightarrow \sum_i -t C_i^\dagger C_{i+1} + h.c. = -ta \sum_i \psi^\dagger(x=ia) \psi(x=(i+1)a) + h.c.$$

$$= -t \int dx [\psi^\dagger(x) \psi(x+a) + \psi^\dagger(x+a) \psi(x)]$$

$$= -t \int dx [(1 - \frac{a}{2} \partial_x) \psi^\dagger(x + \frac{a}{2}) (1 + \frac{a}{2} \partial_x) \psi(x + \frac{a}{2}) + (1 + \frac{a}{2} \partial_x) \psi^\dagger(x + \frac{a}{2}) (1 - \frac{a}{2} \partial_x) \psi(x + \frac{a}{2})]$$

$$= -t \int dx \left\{ \psi^\dagger \psi + \frac{a}{2} [(\partial_x \psi^\dagger) \psi + \psi^\dagger \partial_x \psi] - \frac{a^2}{4} \partial_x \psi^\dagger \partial_x \psi + \psi^\dagger \psi + \frac{a}{2} [(\partial_x \psi^\dagger) \psi - \psi^\dagger \partial_x \psi] \right\}$$

$$= -t \frac{a^2}{2} \int dx \psi^\dagger(x) \partial_x^2 \psi(x) \quad \text{const} \leftarrow -\frac{a^2}{4} \partial_x \psi^\dagger \partial_x \psi$$

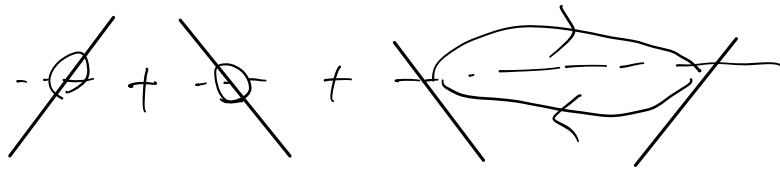
interaction:  $\sum_i C_i^\dagger C_i C_{i+1}^\dagger C_{i+1}$

$$= \sum_i a^2 \psi^\dagger(x) \psi(x) \psi^\dagger(x+a) \psi(x+a)$$

$$= a \int dx \psi^\dagger(x) \psi(x) \psi^\dagger(x+a) \psi(x+a), \quad \psi = e^{ik_F x} \psi_R + e^{-ik_F x} \psi_L$$

$$\psi^\dagger(x) \psi(x) = \psi_R^\dagger \psi_R + \psi_L^\dagger \psi_L + e^{-2ik_F x} \psi_R^\dagger \psi_L + h.c.$$

$$= \frac{F}{\sqrt{2\pi a}} e^{i\Phi}$$



$$\Psi^{\dagger}(x) \Psi(x) \Psi^{\dagger}(x+a) \Psi(x+a)$$

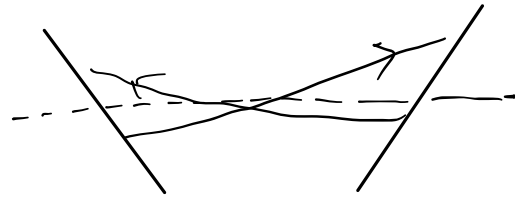
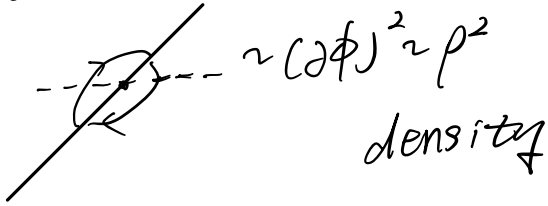
$$= \underbrace{(\phi + \psi + \text{curved})}_{\text{slow}} \times \underbrace{(\psi + \phi + \text{curved})}_{\text{fast}}$$

$$= (S+L) \times (S+L)$$

$$= SS + SL + LS + LL \rightarrow e^{-2ik_F x} \cdot e^{2ik_F x} \rightarrow \text{finite term}$$

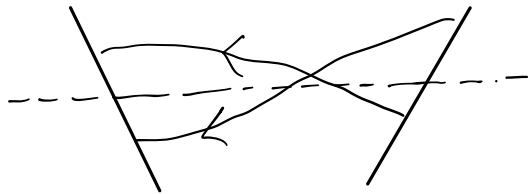
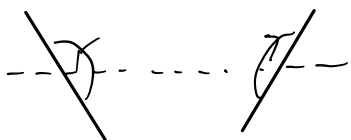
forward (向前) scattering

backward scattering (向后散射)



$\leftrightarrow$  S.S

$\leftrightarrow$  L.L



$\partial\phi \sim \rho$ ,  $\partial\psi \sim \rho$   
k-conservation

$\Delta k \sim 4k_F$  需补偿.  
 $\hookrightarrow e^{-i4k_F x} = e^{-i \cdot n + k_F a}$   
 $\sim 2m\pi$  时  
 density wave 有共振

Sum: interaction: S-S: P-P 作用

L-L: like  $\cos\phi$

$$\begin{aligned} \text{h.c.} + \Psi_L^{\dagger} \Psi_R &= \frac{F_L F_R}{2\pi a} e^{-i\Phi_L + i\Phi_R} + \text{h.c.}, \quad L, R \text{ independent, } F^{\dagger} = F \\ &= \frac{F_L F_R}{2\pi a} e^{-i\Phi_L + i\Phi_R} + \frac{F_R F_L}{2\pi a} e^{i\Phi_L - i\Phi_R} \\ &= \frac{F_L F_R}{2\pi a} (e^{-i\Phi_L + i\Phi_R} - e^{i\Phi_L - i\Phi_R}) \\ &\sim \frac{iF_L F_R}{\pi a} \sin(\Phi_R - \Phi_L) \quad \text{符合平移对称性} \end{aligned}$$

规范要求: L, R 混合, 相位差  $e^{i\theta} \rightarrow$  无  $\partial^2$  things.