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$$P(H) = \prod_{i < j} f(\lambda_i, \lambda_j)$$

$$P(\lambda_1, \dots, \lambda_N) \Rightarrow \text{本征值的联合分布}$$

$$\propto \prod_{i < j} |\lambda_i - \lambda_j|^n e^{-\beta(\sum_j \lambda_j^2)}$$

2. 2:

2.8.4 随机矩阵的联合概率分布.

$$1) H = \begin{pmatrix} h_{11} & h_{12} \\ h_{12} & h_{22} \end{pmatrix} \quad h_{ij} \in \mathbb{R}$$

$$P(\lambda_1, \lambda_2) \sim |\lambda_1 - \lambda_2| e^{-A(\lambda_1^2 + \lambda_2^2)}$$

同样考虑  $3 \times 3$  Matrix.

$$2) H = \begin{pmatrix} h_1 & h_2 + ih_3 \\ h_2 - ih_3 & h_4 \end{pmatrix} \quad 2 \times 2.$$

或  $3 \times 3$ .

~~$P \propto \prod_{i < j} |\lambda_i - \lambda_j|^2 e^{-A(\sum_i \lambda_i^2)}$~~

3)  $1000 \times 1000$  随机矩阵

$$\lambda_1 < \lambda_2 < \dots < \lambda_N \quad N = 1000$$

$$\Delta = \lambda_{i+1} - \lambda_i \quad i \in \mathbb{N}$$

$$P(\Delta) \sim |\Delta|^\alpha e^{-B\Delta^2}$$

$$\Delta = \max_i |\lambda_{i+1} - \lambda_i| \quad P(\Delta) \text{ 分布.}$$

1) 指示:

$$\textcircled{1} \text{ 正規分布 } P(\lambda_1, \dots, \lambda_N) \propto \prod_{i,j} |\lambda_i - \lambda_j| e^{-\frac{1}{4} \sum \lambda_i^2}$$

設  $\theta_i$  为 H 的特征值:

$$P(\theta_1, \dots, \theta_N) \propto \prod_{i,j} |\theta_i - \theta_j| e^{-\frac{1}{4} \sum \theta_i^2}$$

② 物理意义: Dyson Brownian motion.

Dyson = Gao: 對  $P(\theta)$  找一個解。

補充几个结论:

$$\begin{aligned} & \text{Jacobian matrix} \quad \left| \begin{array}{l} dx_1, \dots, dx_N \\ dy_1, \dots, dy_N \end{array} \right| \\ & x_i = x(y) \\ & J = \det \left( \frac{\partial x_i}{\partial y_j} \right) \end{aligned}$$

$x$  向量;  $y$  向量.

$$x = Oy.$$

$$dx_i = d(Oy)_i.$$

$$= O_{ij} dy_j$$

$$\Leftrightarrow \frac{\partial x_i}{\partial y_j} = O_{ij}.$$

$$dx = J dy, \quad J = \det O = 1.$$

推論:  $x, y$  为向量:  $x = Oy$ . ~~且~~  $dx = f(x) dy$ ,  $f(O) = ?$

$$x_{ikj} = (Oy)_{ikj} = O_{ik} y_{kj}$$

$$\frac{\partial x_{ikj}}{\partial y_{kj}} = O_{ik}.$$

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$$X = \begin{pmatrix} 0_{11} & 0_{12} \\ 0_{21} & 0_{22} \end{pmatrix} \begin{pmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{pmatrix}$$

$$x_{11} = 0_{11} y_{11} + 0_{12} y_{21}$$

$$x_{22} = 0_{21} y_{12} + 0_{22} y_{22}$$

$$x_{12} = 0_{11} y_{12} + 0_{12} y_{22}$$

$$x_{21} = 0_{21} y_{11} + 0_{22} y_{21}$$

$$x_1 = 0_{11} y_1 + 0_{12} y_3$$

$$x_2 = 0_{11} y_2 + 0_{12} y_4$$

$$x_3 = 0_{21} y_1 + 0_{22} y_3$$

$$x_4 = 0_{21} y_2 + 0_{22} y_4$$

$$x_{11} \Rightarrow x_1 \quad x_{21} \Rightarrow x_3$$

$$x_{12} \Rightarrow x_2 \quad x_{22} \Rightarrow x_4$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0_{11} & 0 & 0_{12} & 0 \\ 0 & 0_{11} & 0 & 0_{12} \\ 0_{21} & 0 & 0_{22} & 0 \\ 0 & 0_{21} & 0 & 0_{22} \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix}$$

$$= O \otimes I \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix}$$

$$dx = \det(O \otimes I) dy = [\det(O)]^2 dy = dY.$$

$$\text{If } X = OY, \quad dX = f(O)dY.$$

$$\Rightarrow Y = O^T X \quad dY = f(O^T) dX.$$

$$\Leftrightarrow f(O) f(O^T) = 1. \quad f(O) = (\det(O))^k \text{ 假设式}.$$

\* 可用子集故.

另一种可能.

$$\left. \begin{array}{l} X = O^T Y O \\ H' = O^T H O \end{array} \right\} \Rightarrow dx = (?) dY.$$

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$$Z = OX = Y.$$

$$\begin{aligned} dZ &= f(O) dX. \quad | \quad dX = f(O) f(O^T) dY = dY \\ dZ &= f(O) dY. \end{aligned}$$

与之类似。

符号:  $H = O^T \Theta O$      $\Theta = \begin{pmatrix} \theta_1 & & 0 \\ & \ddots & \\ 0 & & \theta_N \end{pmatrix}$

$$H: 1+2+\dots+N = \frac{(N+1)N}{2}$$

$$\text{求 } \theta \text{ 时 } N^2 \Rightarrow O \text{ 中 } 1+2+\dots+N-1 = \frac{N(N-1)}{2}$$

$$\begin{aligned} \Theta &= e^h & | & 1+2+\dots+N-1 = N(N-1)/2 \\ O^T O &= I \Rightarrow h^T = -h. & | & \end{aligned}$$

$$\begin{cases} \theta_1, \dots, \theta_N \end{cases}$$

$$\begin{cases} p_1, p_2, \dots, p_l & l = \frac{N(N-1)}{2} \end{cases}$$

$p_i \in I$  矩阵

$h$  矩阵。

$$J(\Theta, p) = \det \left( \frac{\partial H_{ij}}{\partial \Theta}, \frac{\partial H}{\partial p} \right)$$

$$\text{to } \frac{\partial H_{ij}}{\partial p_\mu}, \frac{\partial H_{ij}}{\partial \theta_\nu}$$

$$\text{calculate } \frac{\partial H_{ij}}{\partial p_\mu}, \frac{\partial H_{ij}}{\partial \theta_\nu} \quad | \quad \text{Wigner 1950.}$$

$\Downarrow$   
 对  $O$  求  $\frac{\partial}{\partial p_\mu}$       对  $\Theta$  求  $\frac{\partial}{\partial \theta_\nu}$

$$H = O^T \Theta O, \quad \frac{\partial H}{\partial p_\mu} = \frac{\partial O^T}{\partial p_\mu} \Theta O + O^T \Theta \frac{\partial O}{\partial p_\mu}$$

$$O^T O = I \Rightarrow = O^T \left( O \frac{\partial O^T}{\partial p_\mu} \Theta \right) O$$

$$+ O^T \Theta \frac{\partial O}{\partial p_\mu} O^T O$$

$$\left. \begin{aligned} 0 \frac{\partial O^T}{\partial P_\mu} &= S_\mu^m & \frac{\partial O}{\partial P_\mu} O^T &= -S_\mu^m \\ 0 \cdot \frac{\partial O^T}{\partial P_\mu} + \frac{\partial O}{\partial P_\mu} O^T &= \frac{\partial}{\partial P_\mu} (O O^T) = 0 \end{aligned} \right\}$$

$$\Rightarrow \frac{\partial H}{\partial P_\mu} = O^T [S^m(\mathbb{H}) - \mathbb{H} S^m] O$$

$$O \left( \frac{\partial H}{\partial P_\mu} \right) O^T = S^m(\mathbb{H}) - \mathbb{H} S^m$$

$$\left| \frac{\partial H}{\partial \theta_\nu} = O^T \frac{\partial (\mathbb{H})}{\partial \theta_\nu} O \quad \Rightarrow \quad O \frac{\partial H}{\partial \theta_\nu} O^T = \frac{\partial (\mathbb{H})}{\partial \theta_\nu} \right.$$

$$S^m = S^m(p) \text{ 定義を述べる}.$$

$$O \frac{\partial H}{\partial P_\mu} O^T = S^m(\mathbb{H}) - \mathbb{H} S^m.$$

すなはち  $\alpha, \beta$  について

$$\begin{aligned} \left( O \frac{\partial H}{\partial P_\mu} O^T \right)_{\alpha\beta} &= O_{\alpha j} \frac{\partial H_{jk}}{\partial P_\mu} (O^T)_{kj\beta} \\ &= O_{\alpha j} O_{\beta k} \frac{\partial H_{jk}}{\partial P_\mu} = S^m(\mathbb{H}) - \mathbb{H} S^m \\ &= S^m_{\alpha\beta} (O_\beta - O_\alpha) \quad \text{ただし } O_\alpha - O_\beta = S^m(\mathbb{H}) - \mathbb{H} S^m. \end{aligned}$$

$$\left( O \frac{\partial H}{\partial \theta_\nu} O^T \right)_{\alpha\beta} = \left( \frac{\partial (\mathbb{H})}{\partial \theta_\nu} \right)_{\alpha\beta} = \alpha_{\alpha\beta} \alpha_{\alpha\nu}.$$

$$\det \left( \frac{\partial H}{\partial \theta_\nu}, \frac{\partial H}{\partial P_\mu} \right) = \det \left( O^T \frac{\partial H}{\partial \theta_\nu} O, O^T \frac{\partial H}{\partial P_\mu} O \right)$$

$$J. = \begin{pmatrix} \alpha_{\alpha\beta} \alpha_{\alpha\nu} \\ S^m_{\alpha\beta} (O_\beta - O_\alpha) \end{pmatrix}$$

展开表示:

$$J = \det \left( \frac{\partial x}{\partial y} \right) = \begin{pmatrix} \frac{\partial x}{\partial \theta} \\ \frac{\partial x}{\partial p} \end{pmatrix}$$

$$J = \det \begin{pmatrix} \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial p} \\ S_{\alpha \beta}^M (\theta_\alpha - \theta_\beta) \end{pmatrix}$$

$$\det \begin{pmatrix} a & b \\ \lambda c & \lambda d \end{pmatrix} = \lambda \det \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

$$\propto \frac{\pi}{\alpha \beta} (\theta_\alpha - \theta_\beta) \det \begin{pmatrix} \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial p} \\ S_{\alpha \beta}^M \end{pmatrix}$$

! 2.5 等价关系.

$$P(\lambda) = \int d(\lambda - \theta) e^{-A \sum_i \theta_i^2} \frac{\pi}{\alpha \beta} |\theta_\alpha - \theta_\beta| f(p) d\theta dp.$$

$$\propto \int d(\lambda - \theta) e^{-A \sum_i \theta_i^2} \frac{\pi}{\alpha \beta} |\theta_\alpha - \theta_\beta| d\theta.$$

物理意义.

$\rightarrow$  布朗运动  $\leftrightarrow$  Brownian motion.

$\frac{1}{k_B T}$   $\leftrightarrow$  温度.

$\theta \leftrightarrow x_\alpha$ . 本征值  $\leftrightarrow$  坐标.

IF:  $P \propto \prod_{i < j} |x_i - x_j| e^{-\frac{\beta}{2} \sum_i x_i^2} \propto e^{-\beta W}$

$\theta$ : 温度.  $W$ : Potential.

$$E_i = - \left( \frac{\partial W}{\partial x_i} \right) = -x_i + \frac{1}{\rho} \sum_{j \neq i} \left( \frac{1}{x_i - x_j} \right)$$

PK Fokker-Planck 方程的表达式:

$$\frac{\partial P}{\partial t} = \sum_j \beta^{-1} \frac{\partial^2 P}{\partial x_j^2} - \frac{\partial}{\partial x_j} (E_j P)$$

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Fokker - Planck eq.

$$\frac{\partial P}{\partial t} + \nabla \cdot \vec{J} = 0 \quad \vec{r} \text{ random force.}$$

$$|\vec{J} = \nabla \vec{P}$$

$$\frac{\partial P}{\partial t} = D \frac{\partial^2 P}{\partial x^2} \quad \vec{r} \text{ 外力, 有扩散.}$$

$$|\frac{\partial^2 x_j}{\partial t^2} = -f \frac{dx_j}{dt} + E(x_j) + g(t)$$

$$| E_j = -\frac{\partial W}{\partial x_j} \quad | \langle g(t) g(t') \rangle = \frac{2k_B T}{f} \delta(t-t')$$

$$| k_B T = \beta^{-1}$$

$$\textcircled{1} f \langle dx_j \rangle = E(x_j) dt.$$

$$\textcircled{2} f \langle dx_j^2 \rangle = 2k_B T dt. \quad \text{大数定律.}$$