

Mc Integral \Rightarrow Markovian chain

类似从简 \rightarrow 复. $x_1 \rightarrow x_2 \rightarrow x_3 \rightarrow \dots \rightarrow x_n \rightarrow x_{n+1}$

$I = \int f(x) p(x) dx = \frac{1}{N} \sum_i f(x_i) \pm \delta I$ $\delta I = \frac{\sigma}{\sqrt{N}} \Rightarrow$ 高维性: Euler-差分 $O(N^{-4/d})$

1) 产生一组数 $\{x_i\}$.

2) $\{x_i\} \rightarrow p(x)$

3) 平台 \sim 收敛.

$\Rightarrow x_i \Rightarrow \vec{x}_i$

$d = 1 + \frac{1}{2} \int_{-\infty}^{\infty} d\vec{k} \rho(\vec{k}) \rightarrow \rho(\vec{k})$

$f(\vec{x})$ 有明确物理意义.

1) $f(\vec{x}) = e^{-\beta H(\vec{x})}$
积分为 $I = \text{Tr}(C e^{-\beta H(\vec{x})}) = \int d\vec{x} e^{-\beta H(\vec{x})}$ 高维积分.
Ising model.

2) Path Integral Mc.

Ising Model.

Ising 证明.

$H = -J \sum_i \sigma_i \sigma_{i+1}$ 无相变

$\sigma_i = \pm 1$. 转移矩阵.

Heisenberg Model.

$H = -J \sum_{\langle ij \rangle} \vec{\sigma}_i \cdot \vec{\sigma}_j$

1944 Onsager.

3d Ising Model. 至今未解决.

积分 $\{x_i\}$.

Metropolis 算法.

Metropolis - Hastings

Gibbs

} 本节课不证

$$\xi \in [0, 1]$$

$$x_{n+1} \begin{cases} x^{new} & \xi < r = \min\left\{1, \frac{P(x^{new})}{P(x_n)}\right\} \\ x_n & \xi > r \end{cases} \text{ . 维持现状.}$$

→ Ising Model.

$$x_n \rightarrow \vec{x}_n \rightarrow \vec{\sigma} = \bigotimes_{i=1}^N z_i = \bigotimes_{i=1}^N z_i \bigotimes_{i=2}^N z_i \bigotimes_{i=3}^N z_i \dots$$

$\vec{\sigma}_n \rightarrow \vec{\sigma}_{n+1}$
→ 随机改变一值

$$N = L^3$$

$$m = \sum_{\{\sigma\}} m(\sigma) e^{-\beta H(\sigma)} / Z$$

$$H(\sigma) = -J \sum_{\langle i,j \rangle} \sigma_i \sigma_j$$

算法: 1) 初始化 ($\sigma = (\sigma^1, \sigma^2, \dots, \sigma^N)$)
2) 随机找 $i \Rightarrow \sigma_i \rightarrow -\sigma_i$

1	2	3	4
5	6	7	8
9	10		

产生格子 (给出序号).
明确相邻关系.

$$3) \text{ 计算 } r = \min\left\{1, \frac{P(x^{new})}{P(x_n)}\right\} \Rightarrow \Delta E$$

$$P(x) = e^{-\beta H(x)} / Z$$

$$P(x^{new}) / P(x_n) = e^{-\beta (H(x^{new}) - H(x_n))} = e^{-\beta \Delta E}$$

$$\text{计算 } \Delta E = H(\vec{\sigma}_n') - H(\vec{\sigma}_n)$$

$$= -2J \sum_{j \in \text{neighbor of } i} \sigma_i^{\text{old}} \sigma_j^{\text{new}}$$

	4	
2	5	4
	3	

$$\Rightarrow \sum_{j \in \text{neighbor of } 5} (\sigma_1 \sigma_5 + \sigma_2 \sigma_5 + \sigma_3 \sigma_5 + \sigma_4 \sigma_5) (-J)$$

$$\text{若 } \sigma_5 \rightarrow -\sigma_5 = \sigma_5$$

$$(\sigma_1 \sigma_5 + \sigma_2 \sigma_5 + \sigma_3 \sigma_5 + \sigma_4 \sigma_5) (-J) (-1)$$

$$\Delta E = 2J (\sigma_1 \sigma_5 + \sigma_2 \sigma_5 + \sigma_3 \sigma_5 + \sigma_4 \sigma_5)$$

$$\textcircled{4} \vec{\sigma}_{nn} = \begin{cases} \text{accept } = \vec{\sigma}' & \text{if } \tau = \min \{1, e^{-\beta \Delta E}\} \\ \text{reject } = \vec{\sigma}_n & \text{otherwise.} \end{cases}$$

$$\text{if } \frac{1}{T} \quad Z = \text{Tr}(e^{-\beta H})$$

$$\downarrow \\ Z = e^{-\beta F}$$

$$F: \text{Free energy} \rightarrow - \frac{\partial \ln Z}{\partial \beta} = \langle H \rangle$$

$$\text{Ising Model. } H = -J \sum_{\langle ij \rangle} \sigma_i \sigma_j + \sum_i h \sigma_i \Rightarrow \int f(\vec{x}) = e^{-\beta H} \quad \vec{x} = \vec{\sigma} = \{\sigma^1, \sigma^2, \dots, \sigma^N\} \\ \sigma^i = \pm 1$$

$$\text{Path Integral } H = -\frac{1}{2m} \frac{d^2}{dt^2} + V(\vec{R})$$

$$Z = \int dR_0 \dots dR_{N-1} e^{-H} = \int dR_0 \dots dR_{N-1} f(\vec{R})$$

$$H = -\Delta \tau \sum_j \left[\frac{m}{2} \frac{(R_{j+1} - R_j)^2}{\Delta \tau^2} + V(R_j) \right]$$

Path Integral. MC.

$$Z = \text{Tr}(e^{-\beta H})$$

$$H = -\frac{1}{2m} \frac{d^2}{dx^2} + V(x)$$

$$\text{if } V(x) \text{ is } \delta \text{ function.} \\ \lim_{\beta \rightarrow 0} Z(\beta) = e^{-\beta E_g}$$

$$Z = \int dx \langle x | e^{-\beta H} | x \rangle$$

$$= \int dx_1 \dots dx_{N-1} \langle x_1 | e^{-\Delta \tau H} | x_1 \rangle \langle x_1 | e^{-\Delta \tau H} | x_2 \rangle \dots \langle x_{N-1} | e^{-\Delta \tau H} | x_N \rangle$$

$$\text{if } \tau \quad \langle x_i | e^{-\Delta \tau (T+V)} | x_{i+1} \rangle$$

$$= \langle x_i | e^{-\Delta \tau T} e^{-\Delta \tau V(x)} | x_{i+1} \rangle$$

$$= \langle x_i | e^{-\Delta \tau T} | x_{i+1} \rangle e^{-\Delta \tau V(x_{i+1})}$$

$$\langle x | e^{-\Delta \tau T} | y \rangle$$

$$\langle x | e^{-\Delta \tau T} | y \rangle$$

$$T = \frac{m(y-x)^2}{2\Delta \tau^2}$$

$$= \int dk \langle x | e^{-\Delta \tau T} | k \rangle \langle k | y \rangle dk = \int dk e^{-\frac{m}{2} \Delta \tau k^2 + i k(x-y)} \\ T = -\frac{m}{2} \frac{d^2}{dx^2} \quad T | k \rangle = \frac{m}{2} k^2 | k \rangle = e^{-\frac{1}{2m} \left(\frac{y-x}{\Delta \tau} \right)^2}$$

总结:

$$I = \int f(\vec{x}) p(\vec{x}) d\vec{x} = \frac{1}{N} \sum_{i=1}^N f(\vec{x}_i)$$

应用: ① 积分:

② $f \sim e^{-\beta H}$, H : energy Hamiltonian.

1) Ising Model.

2) Path Integral MC of H .

③ 求 $V(\vec{x})$ 极值 (kinetic MC)

中心, 大数:

↓

23 节课 - 随机游动: $\langle x^2 \rangle = 2ct$.

2) Jto - lemma.

3) MC simulation. $\delta I = \frac{\sigma}{\sqrt{N}} \sim \text{差分}. N^{-1/d}$

作业

1) 求高维积分.

2) 产生 (2D) $p(x)$ 分布.

3) 求 2d, 3d Ising Model 的相变.