

$$\text{目的} \left\{ -\frac{\hbar^2}{2m} \nabla^2 + V(\vec{x}) \right\} \Psi = E \Psi$$

## 有限差分方法：简单直观

要求：求解： $1d$ ,  $2d$  Schrödinger eq.  
 $d=3 \Rightarrow N^3$

$\Rightarrow$  ① 无<sub>鹽</sub>納化

$$\textcircled{2} \quad \left[ -\frac{1}{2} \frac{d^2}{dx^2} + V(x) \right] \psi(x) = E \psi(x)$$

$$y'(x) = \lim_{h \rightarrow 0} \frac{y(x+h) - y(x)}{h}$$

$$\Rightarrow -\frac{1}{2h^2} (4y_{i+1} + 4y_{i-1} - 2y_i) + v(x_i)y_i = E y_i$$

$\Rightarrow h$  有限. 代替  $y'(x)$

其中  $y_i = y(x_i)$

三对前阵：

$$H = -\frac{1}{2h^2} \begin{pmatrix} -2 & 1 & & & \\ 1 & -2 & 1 & & \\ & 1 & -2 & 1 & \\ & & \ddots & \ddots & \ddots \\ & & & N \times N & \end{pmatrix} + V(x_i)$$

$$f'(x) \approx \frac{f(x+h) - f(x)}{h} + O(h^2)$$

$$f''(x) = \frac{f(x+h) + f(x-h) - 2f(x)}{h^2}$$

⋮

$f(x_n)$

## 特点 (1d)

1) 稀疏矩阵，三对角阵， $O(N^2)$

$$[0]: H = \lambda T + V$$

$$2) N \rightarrow \infty, h = L/N \rightarrow 0$$

$$\left\{ \begin{array}{l} \lambda \rightarrow \infty \\ n \rightarrow \infty \\ \frac{1}{\sqrt{\lambda}} \end{array} \right.$$

## 作业：

1)  $V(x) = \frac{1}{2}m\omega^2 x^2$ ,  $m=1$ , 比对解析结果与数值计算的结果. 体会误差的来源. 大小, 以及误差与  $L, N, h$  的关系.  $h=L/N$ .  
 $h=10^{-3} \sim 10^{-4}$ . 保证计算精度.

$$2) \frac{1}{2}m\omega^2x^2 + A \cos(kx + \phi) = V(x)$$

①故曰求而

② 數據計算 . mma . 算到二阶

~~在数值计算时，结果要与微分状况的结果对照。  
代码要有序，考试要用到。~~

考慮 无穷 滑動性  $\infty$

$$-\frac{1}{2} \frac{d^2}{dx^2} \psi = E \psi \quad \psi \propto \sin(kx)$$

$$\left\{ \begin{array}{l} \psi_{(0)} = \psi_{(L)} = 0 \\ \frac{k^2}{2} = E \\ k_L = n\pi \end{array} \right. \Rightarrow E = \frac{n^2\pi^2}{2L^2}$$

$$H = -\frac{1}{2h^2} \begin{pmatrix} -2 & 1 & & \\ 1 & -2 & 1 & \\ & & \ddots & \end{pmatrix} \lim_{h \rightarrow 0} E_n(h) = \frac{n^2 \pi^2}{2L^2}$$

$$-\frac{1}{2h^2} (\gamma_{i+1} + \gamma_{i-1} - 2\gamma_i) = E \gamma_i$$

女角是什公样子？

$$\text{类似地 } a_{n+1} = x a_n + y a_{n-1}, \quad q^2 = xq + y, \dots$$

$$\text{求解} \quad -\frac{1}{2h^2} (y_{i+1} + y_{i-1} - 2y_i) = E y_i.$$

$$\sum \gamma_i^{\sqrt{-1}} \alpha e^{ikhi}$$

$$-\frac{1}{2\hbar^2} (e^{ik\hbar} + e^{-ik\hbar} - 2) = E$$

$$E = \frac{1}{2h^2} (2 - 2 \cos kh) = \frac{1}{h^2} (1 - \cos kh) = \frac{1}{2} k^2$$

$$\text{边界条件: } \psi_n = c_+ e^{ik_h n} + c_- e^{-ik_h n}$$

$$\left\{ \begin{array}{l} -24_1 + 4_2 = 64_1 \end{array} \right.$$

$$4_{n-1} - 2 \cdot 4_n = \square 4_n$$

代入法解之.

2D推广.

作业: 3) 求两个势的本征态  
 $v = \infty$ .

$$V=0$$

$V = \infty$

$$V_{ij} = \begin{cases} 1 & \text{if } x_i \text{ and } x_j \text{ are adjacent} \\ 0 & \text{otherwise.} \end{cases}$$

$$-\frac{1}{2} \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \varphi + v \dot{\varphi} = E \varphi.$$

$$-\frac{1}{2} \left[ \frac{1}{h^2} ( \varphi_{i+1,j} + \varphi_{i-1,j} - 2\varphi_{ij} ) + \frac{1}{h^2} ( \varphi_{i,j+1} + \varphi_{i,j-1} - 2\varphi_{ij} ) \right] + v_{ij} \varphi_{ij} = E \varphi_{ij}$$

$$= -\frac{1}{2h^2} [ (\varphi_{i+1,j} + \varphi_{i-1,j} + \varphi_{ij+1} + \varphi_{ij-1}) - 4\varphi_{ij}] + v_{ij} \varphi_{ij} = E \varphi_{ij}.$$

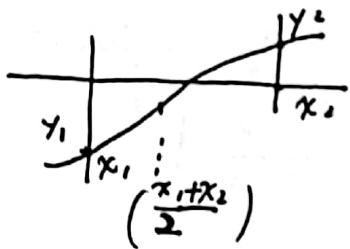
2014年:

1) 梯度矩阵。 $\nabla f \in \mathbb{R}^{n \times n}$ .

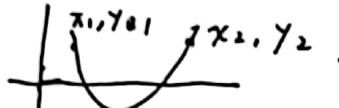
2)  $N^2 \times N^2 \xrightarrow{\text{高阶}} O(N^6)$ .

$$\varphi = \begin{pmatrix} 0 \rightarrow \text{第-3} \\ 0 \rightarrow \text{第-2} \\ \vdots \\ \vdots \end{pmatrix}_{N^2}$$

求根. ( $f'(x) = 0$ )



$$\begin{cases} y_1, y_2 < 0 \\ y_1, y_2 > 0 \end{cases}$$



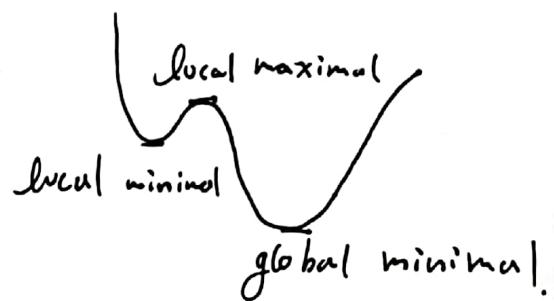
$$x_0 + nh.$$

牛顿法.

思想: | 求根.  
| 极值.

$$F(\vec{x}) \text{ 极值}. \quad f_i = \frac{\partial F}{\partial x_i} = 0.$$

求一个函数的极值等价于求一个函数的根.



牛顿法

$$f(x) = f(x_0) + f'(x_0)(x - x_0)$$

$$f(x_0) + f'(x_0)(x - x_0) = 0$$

$$x = x_0 - \frac{f(x_0)}{f'(x_0)}$$

$$\boxed{x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}} \text{ 牛顿迭代公式}$$

$$\lim_{n \rightarrow \infty} x_n = x^* \Leftrightarrow x^* = x^* - \frac{f(x^*)}{f'(x^*)} \Leftrightarrow f(x^*) = 0.$$

$$\Rightarrow \boxed{x_{n+1} = x_n - p \frac{f(x_n)}{f'(x_n)}}.$$

$$\text{梯度法: } f(\vec{x}) = f(\vec{x}_0) + \frac{\partial f}{\partial \vec{x}} (\vec{x}^i - \vec{x}_0^i) = 0$$

$$\vec{x} = \vec{x}_0 + ( \dots )$$

$$\begin{cases} \text{方程: } y' = f(x, y) \\ \frac{\partial}{\partial t} u = a^2 \Delta^2 u. \end{cases}$$

方法: Runge-Kutta 法. 算法.  $y'(x) = f(x)$ ,  $y = \int_0^x f(x) dx$

mathe matica. Dist, Dsolve  
NDsolve.

matlab ode - 1 程序.

程序: ode45, f90, 1400+.

$y' = f(x, y)$

$y(x_{n+1}) = y(x_n) + f(x_n, y_n) h$ .  $y_{n+1} = y_n + f(x_n, y_n) h$ .

$\rightarrow y_{n+1} = y_n + \frac{1}{2} h [f(x_n, y_n) + f(x_{n+1}, y_{n+1})]$   $\left\{ \begin{array}{l} \text{三点式} \\ \text{四点式} \end{array} \right.$

$$y_{n+1} = y_n + \frac{h}{2} f(x_n, y_n) + \frac{h}{2} f(x_{n+1}, y_n + h f(x_n, y_n))$$

└— Runge-Kutta 5th.  
 $\sim O(h^5)$