

宏观 - 微观

1) 波动方程 $\frac{\partial \phi}{\partial t} = D \frac{\partial^2 \phi}{\partial x^2}$ $D = \text{扩散系数}$
 $\int dx \phi(x, t) = 1$

$\phi \geq 0$

$\frac{\partial \phi}{\partial x} + \frac{\partial \rho}{\partial t} = 0$

$\frac{ds}{dt} = (r + \delta) s \Leftrightarrow d \ln s = r + \delta$

$\Rightarrow \ln s - \ln s_0 = r t + \int_0^t \delta(t') dt'$

Stock price. $\Leftrightarrow s = s_0 e^{r t + \int_0^t \delta(t') dt'}$

$|0^4 (1+0.01) (1-0.01) (1+0.01) (1-0.01)|$

1) 问题在那? chain rule.

2) 正向描述, Ito lemma. (随机分析折价|数学人之一)

大数
定理
 $\langle x^2 \rangle \propto t$

Ito lemma.

$\frac{dx}{dt} = a(x, t) + b(x, t) \xi$ ill-defined.

$\frac{dx}{dt} = a dt$

$dx = a dt + b(x, t) dw$ $dw = \xi dt$

增量

默认: $\frac{dx}{dt} = \frac{x(t+dt) - x(t)}{dt} \Big|_{dt \rightarrow 0^+}$

Wiener 过程 (process), \Rightarrow Brown 运动 $\Rightarrow dw = \zeta dt$.

$w(t) = \int_0^t \zeta(t') dt'$

1) $\overline{w(t)} = 0$

2) $\overline{w^2(t)} = \int_0^t \overline{\zeta(t_1) \zeta(t_2)} dt_1 dt_2$
 $= \sigma^2 \int_0^t dt = \sigma^2 t$

3) $\overline{w(t)w(s)} = \sigma^2 \min(t, s)$ $w(t) = w(s) + \int_s^t \zeta(t') dt'$

4) $\overline{w^2(t)} - \overline{w^2(s)} = \sigma^2(t-s)$
 $= \overline{w^2(s)} + \overline{\left(\int_s^t \zeta(t') dt'\right) w(s)}$

5) $d w^2 = dt \sigma^2$

$dx = a dt + b dw$

$f(x, t)$ 的伊藤方程

$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial t} dt + \frac{1}{2} \frac{\partial^2 f}{\partial x^2} (dx)^2 + \frac{\partial^2 f}{\partial x \partial t} dx dt + \frac{\partial^2 f}{\partial t^2} dt^2$

Chain rule: $\frac{d}{dx} f(g(x)) = f' g'$

$(dx)^2 = a^2 dt^2 + b^2 dw^2 + 2abdtdw$

$d w^2 = \sigma^2 dt$

$dw \sim \sqrt{dt}$

伊藤

$$\frac{df}{dt} = \cancel{f} dw + \cancel{f} dt$$

$$= \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial t} dt + \frac{1}{2} \cdot \frac{\partial^2 f}{\partial x^2} b^2 dt$$

$$= \left. \frac{\partial f}{\partial x} dx + \left(\frac{\partial f}{\partial t} + \frac{1}{2} b^2 \frac{\partial^2 f}{\partial x^2} \right) dt \right.$$

— Ito lemma.

大数 $\Rightarrow = \pi$

~~$ds = r + \frac{1}{2} \sigma^2$~~

$f = \ln s$ $ds = r s dt + \sigma s dw$

$$df = \frac{\partial f}{\partial s} ds + \frac{1}{2} \frac{\partial^2 f}{\partial s^2} ds^2$$

$$= \frac{1}{s} ds - \frac{1}{2} \frac{1}{s^2} (\sigma s)^2$$

$$= \frac{1}{s} (r s dt + \sigma s dw) - \frac{1}{2} \sigma^2 (1-s dt + \sigma s dw)^2$$

$$= r dt + \sigma dw - \frac{1}{2} \sigma^2 dt = (r - \frac{\sigma^2}{2}) dt + \sigma dw$$

$$\Rightarrow df = \cancel{f} (r - \frac{\sigma^2}{2}) dt + \sigma dw$$

$$f(t) = (r - \frac{\sigma^2}{2}) t + \sigma \int_0^t dw + f(0)$$

$$= f(0) + (r - \frac{\sigma^2}{2}) t + \sigma w(t)$$

$$\Rightarrow S = S_0 e^{(r - \frac{\sigma^2}{2}) t + \sigma w(t)}$$

Euler-算法 (Euler method)

$$dx = a dt + b dw$$

$$X_{n+1} = X_n + a(X_n, t_n) dt + b(X_n, t_n) (W_{n+1} - W_n)$$

$$\int_0^T w dw = \sum_n W_n (W_n - W_{n-1})$$

$$\int_0^T w dw = \sum_n W_n (W_{n+1} - W_n)$$

在微分积分中, 结果相同 (同于欧拉)
 但在数值计算中不同

$$\sum_n \overline{W_n (W_n - W_{n-1})} = \sum_n (\overline{W_n^2} - \overline{W_n W_{n-1}})$$

$$= \sum_n [n dt - (n-1) dt] = \sum_n dt = T$$

$$\sum_n \overline{W_n W_{n+1}} - \overline{W_n^2} = \sum_n n dt - n dt = 0$$

$$\int_0^T w dw = \int_0^T d(\frac{w^2}{2} - c) = \frac{w^2}{2} - \text{const}$$

平均值 = $\frac{T}{2} - \text{const}$

Ito lemma

$$f = \frac{1}{2} w^2$$

$$df = \frac{\partial f}{\partial w} dw + \frac{1}{2} \frac{\partial^2 f}{\partial w^2} (dw)^2 = w dw + \frac{1}{2} dt$$

$$\int_0^T df = \int_0^T w dw + \frac{T}{2} \Rightarrow \int_0^T w dw = \frac{w^2}{2} - \frac{T}{2} \Rightarrow \frac{T}{2} - \frac{T}{2} = 0$$

数值 $O(h^3) \rightarrow O(dt^2) \rightarrow O(dt^3)$

Ref:

1) Timothy Saebel: Computational solution of

Stochastic differential equations.

- 2) 刘玉玲. 随机微分方程的数值解. (导师王冉)
- 3) 111 years of Brownian motion. Xin Bian.

$\odot dx = a dt + \sigma dw$

$x \sim p(x, t) \rightarrow \int dx = v t$
 $dv = -\alpha v dt + \sigma dw - f dt$

$m \ddot{x} = -\alpha \dot{x} - f + \xi \quad \dot{x} = v$

$\frac{\partial \phi}{\partial t} = D \frac{\partial^2 \phi}{\partial x^2}$

① Kramers

1940 Brownian motion in a field of force
 and the diffusion model of chemical reactions
 Physica Volume 7, Issue 4, April 1940, Pages 284-3

② Schrödinger - WHAT IS LIFE?

③ Ming chen Wang 王明珠

Uhlenbeck (spin) theory
 On the motion of
 Brownian motion

RMP 1945

④ 1) 如何构造.

2) 马尔可夫链: 1) 连续性方程 2) 耗散率 = 1

例 1. 连续性方程

$$\rho(x, v; t)$$

$$\int \rho(x, v; t) dx dv = 1$$

$$\frac{\partial \rho}{\partial t} + v \cdot \vec{j} = 0$$

$$\frac{d\rho}{dt} = \frac{\partial \rho}{\partial t} + \frac{\partial \rho}{\partial x} \dot{x} + \frac{\partial \rho}{\partial v} \dot{v} = 0 \quad \text{沿特征线}$$

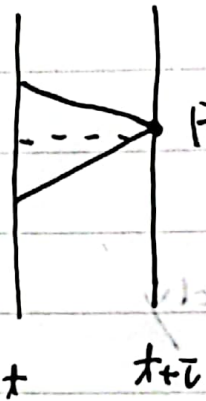
$$= \frac{\partial \rho}{\partial t} + \frac{\partial \rho}{\partial x} (v\rho) + \frac{\partial \rho}{\partial v} (v\rho) = 0$$

$$v \cdot \vec{j} \Rightarrow v = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial v} \right) \quad \vec{j} = (x\rho, v\rho)$$

例 2: Fokker-Planck eq: (Kramer eq.)

核心在 σ^2 : Einstein.

Brownian SDE.



$$P(x, t+\tau) = \int P(x+\Delta, t) P(\Delta) d\Delta$$

$$= \int \left[P(x, t) + \frac{\partial P}{\partial x} \Delta + \frac{1}{2} \frac{\partial^2 P}{\partial x^2} \Delta^2 \right] P(\Delta) d\Delta$$

$$= P(x, t) + 0 + \frac{1}{2} \langle \Delta^2 \rangle \frac{\partial^2 P}{\partial x^2}$$

$$\langle \Delta^2 \rangle = 2D\tau \Rightarrow \text{得到扩散方程}$$

一般性地

$$P(x, t+\tau) = \int P(x+\Delta, t) P(\Delta, x, t, \tau) d\Delta$$

$$= p(x, t) + \sum_{n=1}^{+\infty} \left(\frac{\partial}{\partial x}\right)^n p(x, t) \int \Delta^n \rho_{CCU}(x, t, \tau) d\Delta$$

$$= p(x, t) + \sum_{n=1}^{+\infty} \left(\frac{\partial}{\partial x}\right)^n p(x, t) M_n(x, t, \tau)$$

$$\frac{\partial p}{\partial t} \bar{c} = \sum_{n=1}^{+\infty} \left(\frac{\partial}{\partial x}\right)^n p(x, t) M_n(x, t, \tau)$$

$M_n(x, t, \tau)$
 ① 不能像微分方程求解。
 ② 和 SDE 形式有关。

$$\frac{\partial p}{\partial t} \bar{c} = \sum_{n=1}^{+\infty} \left(\frac{\partial}{\partial x}\right)^n p(x, t) D_n''(x, t)$$

下面理解 $\rho_{CCU}(x, t, \tau)$ 的物理意义。

贝叶斯定理:

$$P(A) = \sum_B P(A|B) P(B)$$

$$p(x, t+\tau) = \int p(y, t) \cdot p(x, t+\tau | y, t) dy$$

$$\rho_{CCU}(x, t, \tau)$$

$$= p(x+\Delta, t+\tau)$$

抽象的 (\vec{x}, \vec{p})