# Finite Group actions on Manifolds

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## • What is symmetry?

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Introdution	Main Theorem and Preparation	Some lemmas for group action	Sketch of proof	

- What is symmetry?
- How to describe symmetry percisely?

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In Mathematics, automorphism group represnts symmetry.

## Definition

A group is a set G, together with an operation(multiplication), and there exists an identity element and the operation satisfies associative law.

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- For example, the set of rotations and reflections is the symmetry information of circle.
- And it indeed forms a group, the operation is composition.





## Defintion

- 1. A subgroup of *G* is a subset *H* which is still a group under the operation of *G*.
- 2. A group G is called abelian group, if the operation is commutative.

## Jordan Theorem

 $\forall n \in N$ , there exists a constant  $C_n$  such that if G is a finite subgroup of GL(n, R) (invertible linear transformation), then G has an abelian subgroup A,  $[G : A] \leq C_n$ .

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## Definition

A *n* dimensional smooth manifold is locally like  $R^n$ , and with smooth condition.

- Homology of manifold are alebraic information of manifold, can be view as ID of the space.Denoted by H<sub>\*</sub>(X).
- Euler characteristc is also algebraic information of a space. Denoted by  $\chi$ .

## Let's see some examples of manifold.



 Roughly speaking, the paper proofs if G is finite subgroup of diffeomorphism group of some manifold, then it satisfies the Jordan property.

## Notation

Suppose that C is a set of finite groups, in the proof, we let C be the set of finite subgroups of Diff(X).

- P(C) be the set of all  $T \in C$ , the order of T is a prime power.
- We denote by T<sub>A</sub>(C) the set of all T ∈ C such that there exist primes p and q, an abelian Sylow p-subgroup P of T, and a normal abelian Sylow q-subgroup Q of T, such that T = PQ.

## Definition

Let c and d be positive integers. We say that a set of groups C satisfies (the Jordan property) J(c, d), if each  $G \in C$  has an abelian subgroup A such that  $[G : A] \leq c$  and A can be generated by d elements.

#### Lemma 3.2

Let *d* and *M* be positive integers. Let *C* be a set of finite groups which is closed under taking subgroups and such that  $P(C) \cup T_A(C)$  satisfies J(M, d). Then there exists a positive integer  $C_0$  such that *C* satisfies  $J(C_0, d)$ .

## Theorem 1.2

Let X be a smooth manifold belonging to one of following three collections, if finite group G acting effectively and smoothly on X, then G satisfies J(C,d), and C,d **depending only on** dimX,  $H_*(X)$ .

- 1. Acyclic manifolds,  $H_0(X) = \mathbb{Z}, H_i(X) = 0, i > 0.$
- **2**. Connected compact manifolds with  $\chi \neq 0$
- 3.  $H_*(X,\mathbb{Z}) \simeq H_*(S^n,\mathbb{Z})$
- Since G acting effectively and smoothly on X, G is a subgroup of Diff(X).

For group action, we have following lemma.

### Lemma 2.1

Let a finite group  $\Gamma$  act effectively and smoothly on a **connected** manifold X, and let  $x \in X^{\Gamma}$ . Then we get an inclusion  $\Gamma \to GL(T_xX) = GL(n, \mathbb{R})$ .

For *p*-group action case, we have following lemma.

#### Lemma 2.2

*p* be a prime, let X be a  $\mathbb{Z}_p$  acyclic manifold,  $\mathbb{Z}_p$  acts on X, then *F* (fix point space) is not empty, and *F* is  $\mathbb{Z}_p$  acyclic manifold.

## Lemma 2.3

Let Y be a **compact** smooth manifold, satisfying  $\chi(Y) \neq 0$ . Let p be a prime, and let G be a finite p-group acting smoothly on Y. Let r be the biggest nonnegative integer such that  $p^r$  divides  $\chi(X)$ . There exists some  $y \in Y$  whose stabilizer  $G_y$  satisfies  $[G:G_v] \leq p^r$ .

#### Lemma 2.4

Let X be a manifold, let p be a prime, and let G be a finite *p*-group acting continuously on X. We have

$$\sum_{j} b_{j}(X^{\mathsf{G}}, \mathbb{Z}_{p}) \leq \sum_{j} b_{j}(X, \mathbb{Z}_{p})$$

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• For  $T_A(C)$  type group action, we have following.

### Lemma 4.2

Suppose that X is a smooth connected manifold and that  $G \in T_A(C)$ . Assume that there is a G-invariant **connected** submanifold  $Y \subset X$ . Let  $G_Y$  be the group consisting of all diffeomorphisms of Y which are induced by restricting to Y the action of the elements of G. Let  $r := \dim X - \dim Y$ . If  $G_Y$  is abelian, then there is an abelian subgroup  $A \subset G$  satisfying  $[G : A] \leq r!$ .

## Sketch of proof of case 1

- For *p*-group case, by lemma 2.2, X<sup>G</sup> is F<sub>p</sub> acyclic, therefore it is nonempty and connected, then by lemma 2.1, G is subgroup of GL(n, R), then use Jordan theorem.
- For  $T_A(C)$ -group case, let  $G = PQ, Y = X^Q$ , for the same reason, we have Y is nonempty and connected.
- Since Q is normal in G, Y is G-invariant space, by lemma 4.2, G has Jordan property.

## Sketch of proof of case 2,3

- *p*-group case, by lemma 2.3, there is a point *x*,  $[G : G_x] \leq p^r$ .
- By lemma 2.1  $G_x$  is the subgroup of  $GL(T_x) = GL(n, \mathbb{R})$ , then use Jordan theorem,  $G_x$  has Jordan property, so G has.
- *T<sub>A</sub>(C)* case, first find *Q'* ⊂ *Q*, which is normal in *G*, and it has fix point.
- Then, by lemma 2.4, the component of X<sup>Q'</sup> is bounded, for a component Y, find P' ⊂ P which the fix point space is not empty, and P' preserves x, then for P'Q' use lemma 4.2.
- Case 3, p-group case is known, for T<sub>A</sub>(C) group case, the key thing is to use Borel formula.

# Summary

- A finite group acting effectively and smoothly on three types of manifolds, then it has Jordan property.
- The main idea of proof is to reduced to *p*-group case and T<sub>A</sub>(C)group case.
- For *p*-group case, we find a fix point then use 2.1.
- For  $T_A(C)$ , we find a submanifold, and using lemma 4.2.

# Summary

- The theorem reflects the symmetry information of some geometric spaces.
- For example, The finite subgroups of SO(3) (rotation group of 3 dimensional space) exactly corresponds to all regular polyhedrons and sphere!
- What about other manifolds(Spaces)?