

1. In implementing time-dependent Fourier representations, we employ sampling in both the time and frequency dimensions. In this problem we investigate the effects of both types of sampling.

Consider a sequence  $x[n]$  with conventional Fourier transform:

$$X(e^{j\omega}) = \sum_{m=-\infty}^{\infty} x[m]e^{-j\omega m}$$

- (a) If periodic function  $X(e^{j\omega})$  sampled at frequencies  $\omega_k = 2\pi k / N, k = 0, 1, \dots, N-1$ , we obtain

$$\tilde{X}[k] = \sum_{m=-\infty}^{\infty} x[m]e^{-j\frac{2\pi}{N}km}$$

These samples can be thought of as the discrete Fourier transform of the sequence  $\tilde{x}[n]$  given by

$$\tilde{x}[n] = \sum_{k=0}^{N-1} \frac{1}{N} \tilde{X}[k]e^{j\frac{2\pi}{N}kn}$$

Show that

$$\tilde{x}[n] = \sum_{r=-\infty}^{\infty} x[n+rN]$$

- (b) What are the conditions on  $x[n]$  so that no aliasing distortion occurs in the time domain when  $X(e^{j\omega})$  is sampled?

- (c) Now consider “sampling” the sequence  $x[n]$ ; i.e., let us form the new sequence

$$y[n] = x[nM]$$

consisting of every  $M^{th}$  sample of  $x[n]$ . Show that the Fourier transform of  $y[n]$  is:

$$Y(e^{j\omega}) = \frac{1}{M} \sum_{k=0}^{M-1} X(e^{j(\omega - 2\pi k)/M})$$

In proving this result you may wish to begin by considering the sequence:

$$v[n] = x[n]p[n]$$

where

$$p[n] = \sum_{r=-\infty}^{\infty} \delta[n+rM]$$

Then note that  $y[n] = v[nM] = x[nM]$ .

- (d) What are the conditions on  $X(e^{j\omega})$  so that no aliasing distortion in the frequency

domain occurs when  $x[n]$  is sampled?

2. A linear time-invariant system has the transfer function,

$$H(z) = 8 \left[ \frac{1 - 4z^{-1}}{1 - \frac{1}{6}z^{-1}} \right]$$

- (a) Determine the complex cepstral coefficients,  $\hat{h}(n)$ , for all  $n$ .
- (b) Plot  $\hat{h}(n)$  versus  $n$  for the range  $-10 \leq n \leq 10$ .
- (c) Determine the (real) cepstrum coefficients,  $c[n]$ , for all  $n$ .

3. A casual LTI system has system function:

$$H(z) = \frac{1 - 4z^{-1}}{1 - 0.25z^{-1} - 0.75z^{-2} - 0.875z^{-3}}$$

- (a) Use the Levinson-Durbin recursion to determine whether or not the system is stable.
- (b) Is the system minimum phase?