

## 回顾基本的 Brown Motion

$$dx = \mu dt + \sigma dw \Leftrightarrow P(x, t) \Leftrightarrow \frac{\partial P}{\partial t} = D \frac{\partial^2 P}{\partial x^2}$$

↑ 宏观过程
↓ 宏观分布
↑ Brown motion

Fokker-Planck equation

$$\left\{ \begin{array}{l} \frac{\partial P}{\partial t} + \nabla \cdot \vec{J} = 0 \\ \vec{J} = \mu P - \frac{1}{2} \partial_x \sigma^2 P \end{array} \right\} \Rightarrow \int dx p(x) = 1$$

$P(x, t) \geq 0$

如果我们已知  $P(x, t)$  问其对应的随机过程 (逆向) 更困难

$$dx = (\quad) dt + (\quad) dw ?$$

上一节课 ① Random matrix  $\Rightarrow$  联合概率分布 (本征值)

$$P(\lambda_1, \lambda_2, \dots, \lambda_n) \propto \prod_{i < j} |\lambda_i - \lambda_j|^{\beta} e^{-\frac{1}{2} \sum_i \lambda_i^2}$$

② Disordered many-body model

$$H = H_{\text{mean}} + H_{\text{disorder}}$$

$$\frac{\partial}{\partial t} u = A \nabla^2 u + B u^4 + \eta$$

今天 已知  $P(\lambda_1, \lambda_2, \dots, \lambda_n) \propto \prod_{i < j} |\lambda_i - \lambda_j|^{\beta} e^{-\frac{1}{2} \sum_i \lambda_i^2}$

问  $\lambda_i$  满足什么样的随机过程

①  $\lambda_i$  本征值  $\Rightarrow$  理解为第  $i$  个粒子的位置

② 目的.  $P$  是数学结论, 还是有不一样的物理意义?

$$\left\{ \begin{array}{l} dx_i = \mu_i dt + \bar{\sigma}_i dW_i \\ \text{其中 } \mu_i \text{ 和 } \bar{\sigma}_i \end{array} \right. \rightarrow \text{potential.}$$

$$\mu_i \Rightarrow \text{drift term} \quad \frac{dx_i}{dt} = \bar{f} \Leftrightarrow dx_i = \bar{f} dt$$

Ref: ① Mehta 随机过程 第九章

② Dyson 原始论文, 1962. "A Brownian Motion Model" for the eigenvalues of a Random matrix"

$$\bar{F} = c e^{-\beta W} = c \prod_{i,j} |x_i - x_j|^\beta e^{-\frac{\beta}{2\alpha^2} \sum_i x_i^2}$$

$$W = -\sum_{i,j} \ln|x_i - x_j| + \sum_{i=1}^N \frac{1}{2\alpha^2} x_i^2 \quad \text{Potential.}$$

↓ 谐振势能

Coulomb gas model.  $\bar{E}(x_i) = -\frac{\partial W}{\partial x_i}$

$$\frac{d^2 x_i}{dt^2} = -\int \frac{dx_j}{dt} + \bar{E}(x_i) + A_i(t)$$

↑ 外力      ↑ 随机力

$$\beta = \frac{1}{k_B T}$$

$$\langle x_i(t) x_j(t') \rangle = \frac{2k_B T}{\Gamma} \delta(t-t')$$

代入 Fokker-Planck equation

$$f \frac{\partial P}{\partial t} = \sum_i k_B T \frac{\partial^2 P}{\partial x_i^2} - \frac{\partial}{\partial x_j} (\bar{E}(x_j) P)$$

稳定解  $\frac{\partial P}{\partial t} = 0$

$$\Rightarrow \sum_j \frac{\partial}{\partial x_j} [k_B T \frac{\partial P}{\partial x_j} - \bar{E}(x_j) P] = 0$$

$$k_B T \frac{\partial P}{\partial x_j} = \bar{E}(x_j) P$$

$$\Rightarrow \bar{E}(x_j) = - \frac{\partial W}{\partial x_j}$$

$$dW = \sqrt{\frac{2}{\beta N}} dW_1 + \frac{1}{N} \sum_{j=0}^L \frac{d\epsilon}{(x_i - k_j)}$$

Dyson  $\Rightarrow$

$$\begin{cases} f(\delta x_i) = \bar{E}(x_i) \delta \epsilon \\ f(\delta x_i^2) = 2k_B T \delta \epsilon \end{cases}$$

下面讨论一个有连线的图像

矩阵:  $M = (M_{ij})_{N \times N} \Rightarrow$  元素  $M_{ij}, j=1, \dots, L$

$P(M_1, \dots, M_L) dM_1 dM_2 \dots dM_L$  为  $[M_i, M_i + dM_i]$  之测度

$$\left\{ \begin{aligned} f(\delta\mu) &= -\mu/a^2 \delta t \\ f(\delta\mu^2) &= g_{\mu} k_B T \delta t \end{aligned} \right. \quad g_{\mu} = \text{const}$$

$$f \frac{\delta P}{\delta t} = \frac{1}{\mu} \left[ \frac{1}{2} k_B T g_{\mu} \frac{\delta^2 P}{\delta \mu^2} + \frac{1}{a^2} \frac{\partial}{\partial \mu} (\mu g_{\mu} P) \right]$$

假设  $\mu$  对角化  $\Rightarrow t + \delta t$ ,  $\mu \rightarrow \mu + \delta\mu$

$\mu_{ii} = \lambda_i$  是在  $t$  时刻的本征值.

$$t \rightarrow t + \delta t \quad \lambda_i' = \lambda_i + \delta\lambda_i$$

利用 = PT Perturbation

$$\delta\lambda_i = \delta\mu_{ii} + \sum_j \left( \frac{|\delta\mu_{ij}|^2}{\lambda_i - \lambda_j} \right)$$

$$\delta\lambda_i = ( ) d\omega_i + \sum_j \left( \frac{|\delta\mu_{ij}|^2}{\lambda_i - \lambda_j} \right)$$

$\lambda_i =$  所附扰函数解

$|\lambda_i - \lambda_j|$  因子.