

关于 sign 一阶的, 正负, = 1/2 阶的 - 正负阶的正负

讨论: 无噪声, 有色噪声 (1d 信号 \rightarrow 4+1d 信号)

$(\theta^2 + g \cos(\theta)) \quad g=0$ 白噪声

\Rightarrow Insulator phase

如本小论文 \rightarrow !!! 用非平凡!!!

2020年 12月30日 第 50

①: 讨论 $k_B T_c = \frac{\pi}{2} J$

② 方法 Poisson summation

$\sum_{n=-\infty}^{+\infty} f(n) = \sum_{k=-\infty}^{+\infty} \tilde{f}(k)$

证明: $\tilde{f}(k) = \sum_n f(n) e^{2\pi i n k} \Rightarrow \tilde{\tilde{f}}(k) = \sum_n \tilde{f}(n) e^{2\pi i n k} \quad (n \text{ 整数})$

$= \sum_n f(n) \sum_m \delta(n-m) = \sum_n f(m)$

$\therefore f(n) = e^{-an^2 - bn}, \quad \tilde{f}(k) = \sqrt{\frac{a}{\pi}} e^{(b - 2\pi i k)^2 / 4a} = \sqrt{\frac{a}{\pi}} e^{-(2\pi k - ib)^2 / 4a}$

有用 $a \rightarrow$ interaction weak $b \rightarrow$ stragg (quasi 平衡)

eg. $a=1.0, b=0.53$

$\sum_n f(n) = 1.90138$
 $\sum_k \tilde{f}(k) = 1.90138$

解: 欧拉求和 $\sum_n f(n) \rightarrow \int_{-\infty}^{\infty} f(x) dx$

RK1: ① 半经典处理 $F=U-TS$ 不- T 可靠 \rightarrow RK1c = $\frac{I}{2} J$

② Thouless (1973) 还有 k) PRL Simon 书有

③ Jose \rightarrow dual Nagaoka 20世纪 CMP 里 第 5 章 第 1 节

指数: $\langle e^{U \rangle} = e^{\langle U \rangle + \frac{1}{2} \langle U^2 \rangle}$

$\langle e^{J \cos \theta} \rangle = e^{\langle J \cos \theta \rangle} \quad \cos \theta = 1 - \frac{\theta^2}{2} + \dots$

$\langle e^{U \rangle} = \langle e^{k \rangle} = e^{\langle k \rangle}$

$\therefore U = 2 \cos \theta = e^{i\theta} + e^{-i\theta}$

$U = e^{i\theta \cos \theta} = e^{\frac{1}{2} \langle e^{i\theta} \rangle + \langle e^{-i\theta} \rangle}$

$\langle U \rangle = e^{\langle i\theta \cos \theta \rangle} = e^{\frac{1}{2} \langle e^{i\theta} \rangle + \langle e^{-i\theta} \rangle}$

$X.G. Wen \quad \theta = \theta_c + \theta_s$

$S = \int \frac{k}{2} (a_n \theta)^2 - g \cos(n\theta_c) + \int \frac{k}{2} (a_n \theta)^2 - g [\cos(n(\theta_c + \theta_s)) - \cos(n\theta_c)] = \int \frac{k}{2} (a_n \theta)^2 + g \frac{n^2}{2} \cos(n\theta_c) \theta_s^2 - n g \sin(\theta_c / \theta_s)$

$\therefore Z = \int D\theta e^{-S} \int D\theta_s e^{-\int \frac{k}{2} (a_n \theta_s)^2} (e^{-g \frac{n^2}{2} \cos(n\theta_c) \theta_s^2} - n \sin(\theta_c / \theta_s))$

- 1st: $\langle \theta^2 \rangle \quad \langle \theta(x) \theta(y) \rangle = g |x-y|$

$e^{-\frac{n^2}{2} g \langle \theta^2 \rangle} \int \cos(n\theta_c)$

$= \sqrt{g} : \langle \theta_1^2(x), \theta_2^2(x) \rangle \langle \theta_1(x), \theta_2(x) \rangle = g_1(x-x')$ 且有
 矩阵 $\langle \theta_1^2(x), \theta_2(x) \rangle^T, \langle \theta_1(x), \theta_2^2(x) \rangle^T$

$(g^2 n^2 \cos(n\theta_1(x)) \cos(n\theta_2(x)))$ 互斥相互作用
 $\downarrow \log | \cos \theta_1 \theta_2 |$

$\int (x^2 - |x+y|)$
 $g^2 n^2 \int \cos(n\theta_1(x)) \cos(n\theta_2(x)) g_1(x-x')$
 $= g^2 n^2 \int \cos(n\theta_1(x)) \cos(n\theta_2(x+y)) g_1(y)$ 互斥, 又有 $y \rightarrow 0(n)$
 \downarrow 才有贡献

$\cos(n\theta_1(x) + n(\theta_2(y)))$
 $= \cos(n\theta_1) [1 - \frac{n^2}{2} y^2 (\theta_2)^2] - \sin(n\theta_1) (n\theta_2 y)$

$\int \cos^2(n\theta_1 + g_2(y)) dx dy$
 $\downarrow \cos^2(n\theta_1) (dx dy) y^2 g_2(y) dy$ 互斥
 $\downarrow \frac{1}{2}(1 + \cos(2n\theta_1))$ meloncut

一阶对相互作用作用, 二阶对相互作用作用 (以 $\theta_1 \rightarrow \theta_1$, 对相互作用作用)
 波函数作用

\therefore 最佳 $S = \int dx [\frac{1}{2} (dx)^2 - g_\lambda \cos(n\theta_1)]$

$k_\lambda = k + \frac{n^2}{8} g^2 k_2 \rightarrow$ 互斥
 $g_\lambda = g - \frac{1}{2} k(10), k(10) = (\frac{1}{2n})^2$

$\rightarrow \frac{1}{2} \int dx \frac{n^2}{k|k|^2} = \frac{n^2}{2\pi k} \ln(\frac{\Lambda}{2})$
 $k_2 = \int dx k|k| n^2 = \int dx (\theta_1(x) \theta_2(x)) \frac{1}{k|k|^2}$
 Ruitai paper

$= \frac{\Lambda^2}{2} \left(\frac{3n^2 \epsilon^4}{2\pi k} \right)$

做完重新整理后 互斥作用 rescaling
 $|k| \leq \frac{2\pi}{\Lambda} \rightarrow |k| \leq \left(\frac{2\pi}{\Lambda} \right) \lambda > 2$

$\int dx \frac{k_\lambda (d\theta)^2 - g_\lambda \cos(n\theta)}{b \frac{2\pi}{\Lambda} \Rightarrow b = \frac{2}{\Lambda} \Rightarrow |k| \leq b\Lambda, k = b k', |k'| \leq \Lambda$

$x = \frac{1}{b} x' \quad \theta_1(x) = \theta_1(\frac{1}{b} x') = 2\theta_1(x')$

$\therefore = \frac{b}{2} \int \left(\frac{1}{b} \right)^2 dx' \left(\frac{d}{d(\frac{1}{b} x')} \theta_1(x') \right)^2$

$= \frac{b^2}{2} \int dx' (d\theta_1(x'))^2$ (不会改变, 是相称, 与 b 无关)

$g_\lambda - 2 = -g_\lambda \left(\frac{1}{b} \right)^2 \int dx' \cos(n\theta_1(x'))$
 $= -g_\lambda \left(\frac{1}{b} \right)^2 \int dx' \cos(n\theta_1(x'))$ $\downarrow z=1$

\Rightarrow rescaling $= \frac{k_\lambda}{2} \int dx' (d\theta_1(x'))^2 - g_\lambda \left(\frac{1}{b} \right)^2 \int dx' \cos(n\theta_1(x'))$
 $= \frac{1}{2} \left(k + \frac{n^2}{8} g^2 k_2 \right) \int dx' (d\theta_1(x'))^2 - \left(g - \frac{1}{2} k(10) \right) \int dx' \cos(n\theta_1(x'))$

$\therefore b = \left(\frac{2}{\Lambda} \right)$, 由其互斥相互作用 $\frac{1}{2} k(b) = \frac{1}{2} \left(k + \frac{n^2}{8} g^2 k_2 \right)$
 $g(b) = - \left(g - \frac{1}{2} k(10) \right) \left(\frac{1}{b} \right)^2$

$\therefore b = \frac{1}{\Lambda} = 1 - \epsilon \Rightarrow \int \frac{k(1-\epsilon)}{2} = \frac{1}{2} \left(k + \frac{n^2}{8} g^2 k_2 \right)$
 $g(1-\epsilon) = -\frac{1}{2} \left(g - \frac{1}{2} k(10) \right)$

\Rightarrow 最佳 $\int \frac{dk}{db} = \frac{-n^2 g}{4\pi k} \Rightarrow \frac{dg}{dk} = -1 \Rightarrow \frac{g}{g^2 \Lambda^4} = -1 \Rightarrow \frac{1}{g \Lambda^4}$
 代入有关系
 Ruitai paper

定义 $k \rightarrow k$

$g \rightarrow g \lambda^2$

k 有些人这样定义

$$\frac{dg}{db} = \frac{2 - \frac{n^2}{4\pi k}}{g}$$

Thickness 任意材料 (膜厚)

$\frac{dy}{db} : A > 1 \Rightarrow y = e^{Ab} \quad \begin{cases} A > 0 \\ A < 0 \end{cases}$

$\textcircled{1} 2 - \frac{n^2}{4\pi k} > 0 \Rightarrow g \rightarrow \infty$ 这时 $(\sin \theta)^2 - g \cos \theta$

$R \rightarrow \infty \rightarrow \text{反射} \rightarrow$ 不相干 $\sin g \cos \theta$ 干涉 \Rightarrow 干涉极大

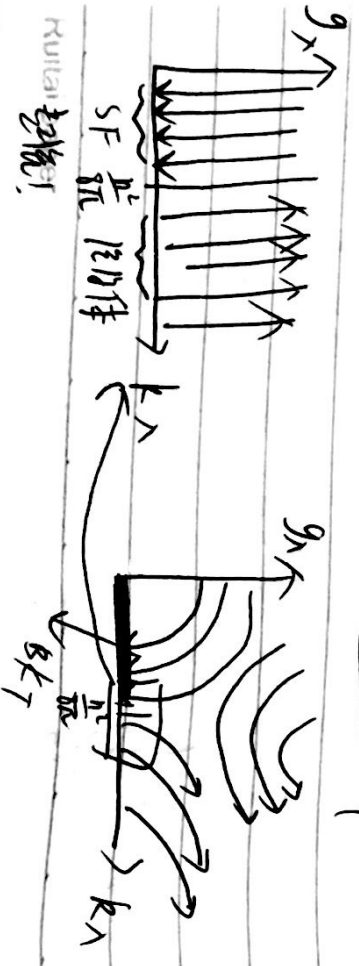


$\textcircled{2} 2 - \frac{n^2}{4\pi k} < 0 \Rightarrow g \rightarrow 0$

结果 $S = f(\sin \theta)^2 \Rightarrow$ SF phase

相速度 $\frac{2 - \frac{n^2}{4\pi k}}{2} = 0 \quad E = \frac{n^2}{8\pi} \quad k = \beta J$

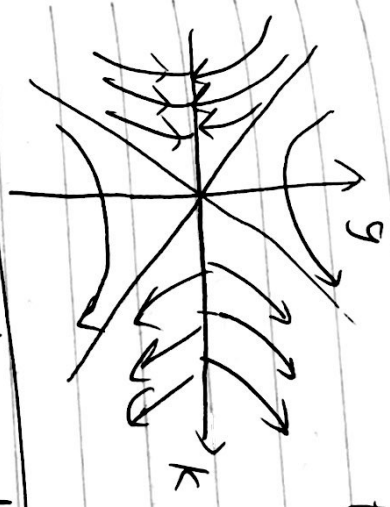
$\Rightarrow \beta J = \frac{n^2}{8\pi} \quad | - \sin \theta = \varphi, \Rightarrow |k_{B1c} = \frac{\pi}{2} J$



Spankan P358 Fig. B.2

$\frac{dg}{db} = kg$
 $\frac{dk}{db} = \frac{n^2}{4\pi k^2} \left(\frac{dk}{db} \right)$

fixed point \Rightarrow fixed node line



固定点或节点线

下节课 Wannier-Kramers duality

技巧性很强, 一定要好好学

本解 $Z = \int_{-\infty}^{+\infty} DB \cdot P_{Bj} e^{\beta J \sum_{ij} \cos(\theta_j - \theta_i)}$ (用傅里叶变换)

非平衡态

Wilson 变换 $\beta J = \frac{2}{\pi} w D$

在加些限制 $\sum_m h(m) = \sum_l |d_l| h(l) e^{2\pi i l \phi}$

possum 之和 $\sum_m h(m) = \sum_l |d_l| h(l) e^{2\pi i l \phi}$

$= |d_l| \sum_l h(l) e^{2\pi i l \phi}$

而 $Z = e^{2\pi i \phi} = \sum_m (\phi - m)$ 建议: 画图, 数值计算

$Z = |DB| \exp \left[-\frac{\beta J}{2} (\theta_a - \theta_j - 2i\phi)^2 + 2\pi i l j \phi \right] |h(l)|$

$= |DB| \sum_m e^{\beta J - \frac{\beta J}{2} (\theta_a - \theta_j - 2\pi m)^2} |h(l)|$

$= |DB| \sum_{l_j} |d_l| e^{\beta J - \frac{\beta J}{2} (\theta_a - \theta_j - 2i\phi)^2 + 2\pi i l j \phi}$

$= |DB| \sum_{l_j} |d_l| e^{\beta J - \frac{\beta J}{2} (\theta_a - \theta_j - 2i\phi)^2 + 2\pi i l j \phi}$

$(\theta_j - \theta_j) - 2(\theta_j - \theta_j) 2\pi \phi + 4\pi \phi^2$

Date: _____

用 \$z\$ 表示 \$e^{i\mathbf{r}\cdot\mathbf{r}'} = \sum_m \delta(\mathbf{r}\cdot\mathbf{r}-m)\$

$$\int d\mathbf{r} e^{i\mathbf{r}\cdot\mathbf{r}'} = \delta(\mathbf{r}-\mathbf{r}')$$

$$\int d\mathbf{r} \sum_{\mathbf{r}'} e^{i\mathbf{r}\cdot\mathbf{r}'} = \sum_{\mathbf{r}'} \delta(\mathbf{r}-\mathbf{r}')$$

$$= \sum_{\mathbf{r}'} e^{-i\mathbf{r}\cdot\mathbf{r}'} \int d\mathbf{r} e^{i\mathbf{r}\cdot(\mathbf{r}-\mathbf{r}')} = \sum_{\mathbf{r}'} \delta(\mathbf{r}-\mathbf{r}')$$



$$Z_{12}(\theta_1, -\theta_2) + Z_{16}(\theta_1 - \theta_6)$$

$$+ Z_{10}(\theta_1 - \theta_4) + Z_{18}(\theta_1 - \theta_8)$$

$$\dots e^{i\theta_1(Z_{12} + Z_{10} + Z_{16} + Z_{18})}$$

重要技巧 \$Z_{ij} = -Z_{ji}\$ \$Z_{ij}(\theta_1 - \theta_j) = Z_{ji}(\theta_j - \theta_1)\$

令 \$Z_{ij} \rightarrow Z_{ij}(1)\$ 为 site index

$$\frac{Z_{ij}}{2\beta J} \rightarrow -i Z_{ij}(\theta_1 - \theta_j) = \frac{Z_{ij}(1)}{2\beta J} - i Z_{ij}(1)(\theta_1 - \theta_j)$$

$$\dots = \sum_{\mathbf{r}} e^{-\frac{2\beta J}{2\beta J} \sum_{\mathbf{r}'} Z_{\mathbf{r}\mathbf{r}'}(1) \theta_{\mathbf{r}'} + i \sum_{\mathbf{r}} (Z_{\mathbf{r}\mathbf{r}'}(1) - Z_{\mathbf{r}'}(\mathbf{r})) \theta_{\mathbf{r}}}$$

$$\Rightarrow \delta \left[\sum_{\mathbf{r}} (Z_{\mathbf{r}\mathbf{r}'}(1) - Z_{\mathbf{r}'}(\mathbf{r})) \right] \rightarrow \text{一堆 (完全) 约束}$$

约束 在 dual lattice 上 不完全约束, 限制了

$$a - c + b - d = 0$$

$$\mathbf{r} \times \mathbf{z}(\mathbf{r}) = (Z_x(\mathbf{r}), Z_y(\mathbf{r}))$$

$$= (\mathbf{r} \times \mathbf{\hat{n}})$$

$$\Rightarrow \begin{cases} Z_x = d \times n \\ Z_y = d \times n \end{cases}$$

$$= \begin{cases} n(r_x) - n(r-y) \\ n(r) + n(r-x) \end{cases}$$

约束

$$\mathbf{\hat{n}} = (0, 0, n)$$

$$n(Z_x(r) - Z_x(r-x) + Z_y(r) - Z_y(r-x)) = 0$$

自动满足

在 dual lattice 上约束 约束是 冗余的

$$Z_{ij}(r) \in \mathbb{Z} \Rightarrow \text{约束的约束}$$

$$\Rightarrow \sum_{\mathbf{r}} e^{-\frac{2\beta J}{2\beta J} \sum_{\mathbf{r}'} Z_{\mathbf{r}\mathbf{r}'}(1) \theta_{\mathbf{r}'} - Z_{\mathbf{r}}(\mathbf{r})}$$

\$\Rightarrow\$ 现在可以求出约束的 冗余 \$\Rightarrow\$ 约束 - 冗余的 约束 冗余的 冗余 \$\Rightarrow\$ 冗余的冗余

$$\therefore Z = \int_{\mathcal{D}} e^{R \cos(\theta_1 - \theta_2)}$$

$$= \int_{\mathcal{D}} e^{r_1^2} \delta(r_1 - r_2) \delta(\theta_1 - \theta_2)$$

史詩
波工作 = $Z = \int_{\mathcal{D}} e^{-\frac{1}{2\beta J} (M(r) - N(r - \mu))} Z \rightarrow \text{Hilbert}$

史... 這是有美觀

\Rightarrow 恢復 poisson 分布